

1. Long-range dependence (LRD) [1, 2]

Autocorrelation: X_t is called a process with long-range dependence if there exists a real number $\delta \in (0, 1)$ and a constant c_{ρ} such that: $\lim_{\tau \to \infty} \frac{\rho_{X,\tau}}{c_{\rho}\tau^{-\delta}} = 1$ where $\rho_{X,\tau}$ is the autocorrelation sequence of X_t at time lag τ .

Spectral density: X_t is called a process with long-range dependence if there exists a real number $\delta \in (0, 1)$ and a constant c_S such that: $\lim_{f\to 0} \frac{S_X(f)}{c_S |f|^{-\delta}} = 1$ where $S_X(f)$ is the spectral density of X_t at frequency f.

2. Low-frequency earthquakes (LFEs)

- Small magnitude earthquakes ($M \sim 0 2$).
- Reduced amplitudes at frequencies greater than 10 Hz.
- Earthquake source located close to the plate interface.
- Grouped into families: All LFEs from a given family originate from the same small patch.
- Dozens of LFEs within a few hours or days, followed by weeks or months of quiet.

5. Summary

- LRD: Slow rate of decay of the statistical dependence between two points with increasing time interval between the points.
- Evidence of LRD in LFE catalogs.
- Earthquake occurrence times → Discrete time series = Number of earthquakes per unit of time.
- Graphical methods to estimate either the Hurst parameter *H* or the fractional differencing parameter *d*.

Long-range dependence in low-frequency earthquake catalogs Ariane Ducellier University of Washington

3. Estimators [3]

Aggregated time series: $X^{(m)}(k) = \frac{1}{m} \sum_{i=(k-1)m+1}^{km} X_i$
First absolute moment: $AM^{(m)} = \frac{m}{N} \sum_{k=1}^{\frac{N}{m}} \left X^{(m)}(k) - \overline{X} \right $
Sample variance: $\widehat{Var}X^{(m)} = \frac{m}{N}\sum_{k=1}^{\frac{N}{m}} \left(X^{(m)}(k) - \overline{X}\right)^2$
Average $VR^{(m)}$ over k of the sample variance of the residuals of the linear regression of the partial sums of the time series.
$\frac{1}{m} \sum_{t=1}^{m} \left(Y_k^{(m)}\left(t\right) - a - bt \right)^2 \text{ and } Y_k^{(m)}\left(t\right) = \sum_{i=(k-1)m+1}^{(k-1)m+t} X_i$
R/S statistics: $R/S_k^{(n)} = \frac{R_k^{(n)}}{S_k^{(n)}}$, $k = 0, \cdots, K-1$ with:

 $R_{k}^{(n)} = \max_{1 \le t \le n} \left[Y_{k}(t) - \frac{t-1}{n} Y_{k}(n) \right] - \min_{1 \le t \le n} \left[Y_{k}(t) - \frac{t-1}{n} Y_{k}(n) \right]$ $S_{k}^{(n)} = \text{Square root of sample variance of } X(i) \text{ and } Y_{k}(t) = \sum_{i=\left\lceil \frac{N}{K} \right\rceil k+1}^{\left\lceil \frac{N}{K} \right\rceil k+1} X_{i}$

Periodogram: $I(f) = \frac{1}{2\pi N} \left| \sum_{t=1}^{N} X_t e^{itf} \right|^2$ where *f* is the frequency.

Asymptotic behavior of the graphical estimators

Estimator	Asymptotic behavior	For
$AM^{(m)}$	m^{H-1}	Large m
$\widehat{Var}X^{(m)}$	m^{2d-1}	Large N/m and m
$VR^{(m)}$	m^{2d+1}	Large m
$R/S_k^{(n)}$	$n^{d+rac{1}{2}}$	Large n
$I\left(f ight)$	$ f ^{-2d}$	$\nu \to 0$



Distribution of the value of H or d for all the time series in each LFE catalog for the five methods of estimation. For better comparison between the distributions of H and d, I plotted H - 0.5 instead of H.

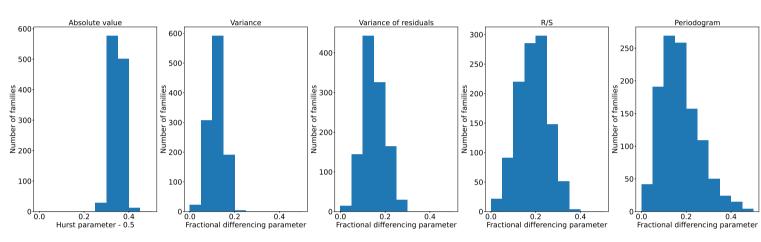


Figure 1: 1120 time series from the LFE catalog of Frank *et al.* (2014) in Mexico.

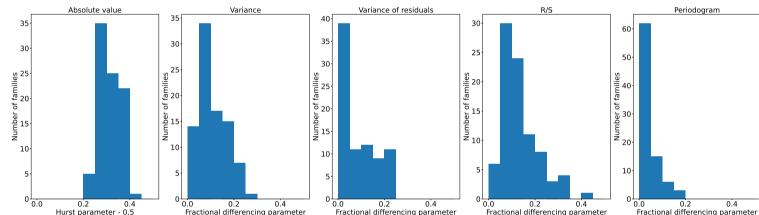


Figure 2: 88 time series from the LFE catalog of Shelly (2017) in the San Andreas Fault.

6. References and Acknowledgements

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