# Robust Estimation for the Annual Survey of Public Employment & Payroll Using Mixture of Linear Mixed-Effect Models with the MCMC Procedure

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### Abstract

The Public Sector Sample Design and Estimation Branch uses Horvitz-Thompson, Empirical Best Linear Unbiased Prediction (EBLUP) and Bayesian approach to small area estimation (SAE) for the Annual Survey of Public Employment & Payroll (ASPEP). The EBLUP estimator is based on a linear mixed-effect model (LMM) with errors that are assumed to be normally distributed. In this study we provide a robust estimate for the total number of full-time employees in the ASPEP using Bayesian method for a LMM assuming errors governed by a mixture of normal distributions. We specify the Markov Chain Monte Carlo (MCMC) procedure in order to produce samples for the LMM's parameter space. We then compare our research method to the existing methods being used at the U.S. Census Bureau. The Census of Governments (CoG), Survey of Public Employment & Payroll data of 2007 and 2012 were used for the evaluation of this research.

**Key Words:** Linear mixed-effect models, Mixture models, Bayesian method, MCMC procedure.

#### 1 Introduction

The presence of outliers in the ASPEP data requires a robust regression approach when fitting linear mixed-effect models (LMMs). The error term in LMMs is assumed to be normally distributed. Outliers often appear when this assumption is violated. To accommodate outliers we may use error terms that follow a t-distribution that has relatively thicker tails (e.g. McLachlan and Basford [12] (1987), McLachlan and Peel [13] (2000), McLachlan, Ng, and Bean [14] (2006), Bell and Huang [2] (2006), Staudenmayer, Lake and Wand [17] (2009)). A more flexible way is to assume that the data are drawn from a finite mixture model, including the normallydistributed error models as a special case, in capturing a broader range of non-normal behaviors (see McLachlan and Peel [13] (2000), McLachlan and Basford [12] (1987), and McLachlan et al. [14] (2006)). Figure 1 shows the standard normal distribution, the t-distribution with 4 degrees of freedom, and a mixture of normal distributions. Notice that the mixture of normal distributions has relatively thicker tails among the three. In reality, real data often show more than one mode, and estimates using mixture models appear more reliable than the others.

Any views expressed are those of the authors and not necessarily those of the U.S. Census Bureau.

Figure 1:  $\mathcal{N}(0,1)$ ,  $t_4(0,1)$  and Mixture  $0.75\mathcal{N}(0,1) + 0.25\mathcal{N}(0,10)$ 



**Comparison of Distributions** 

The mixture model parameters can be deduced by using Expectation-Maximization (EM) algorithm (e.g. McLachlan and Basford [12] (1987), De Veux and Krieger [5] (1990), McLachlan and Peel [13] (2000), Tadjudin and Landgrebe [18] (2000), Hall and Wang [10] (2005), McLachlan et al. [14] (2006), Gershunskaya and Lahiri [9] (2010), Trinh and Tran [19] (2016)), Gibbs Sampling or the MCMC procedure (e.g. Wand et al. [20] (1994), Woodworth [21] (2004), Bolstad [3, 4] (2007, 2010) using posterior sampling as indicated by Bayes' theorem:

$$P(\theta|y) = \frac{P(\theta)P(y|\theta)}{P(y)} \propto P(\theta)P(y|\theta)$$
(1.1)

where  $P(y|\theta)$  is the likelihood function or the density of the data y given the parameters  $\theta$ ;  $P(\theta)$  is the prior density of the parameters; and  $P(\theta|y)$  is the posterior density of the parameters given the data. Once the likelihood and the prior density are specified, inferences on parameters can be made by using samples drawn from the posterior distribution produced by the MCMC simulation.

This report is organized as follows: In Section 2, three Hierarchical Bayes (HB) estimators (using normal, t, and mixture of normal distributions) are specified in order to estimate the total number of full-time employees for various government functions in the ASPEP data. Section 3 shows convergence diagnostics and test results. The 2012 ASPEP data (in Alabama, California, Georgia, Illinois, and Louisiana) are used, with the 2007 ASPEP data as auxiliary information. The performance of the three HB estimators is assessed by Relative Root Mean Square Errors (RRMSE).

#### 2 Robust Estimations

To accommodate outliers in the ASPEP data, three LMMs will be used: normal, t (e.g. Lange, Little, and Taylor [11] (1989), Bell and Huang [2] (2006)), and mixture of normal distributions (e.g. De Veux and Krieger [5] (1990), Gershunskaya and Lahiri [9] (2010)). We will fit these models using Bayesian methods.

Let  $y_{mk}$  denote the value of the  $k^{\text{th}}$  unit within the  $m^{\text{th}}$  government function (area). We are interested in estimating the total  $Y_m = \sum_{k=1}^{N_m} y_{mk}$  for m = 1, ..., M ( $N_m$ : number of units of the  $m^{\text{th}}$  area; M: number of areas). An estimator of  $Y_m$  is given by:

$$\widehat{Y}_m = y_m + \widehat{Y}_{mr} \tag{2.1}$$

$$= N_m [f_m \overline{y}_m + (1 - f_m) \overline{Y}_m r]$$
(2.2)

where  $y_m = \sum_{k=1}^{n_m} y_{mk}$ : the sum of the sample values;  $\widehat{Y}_{mr}$  is a predictor of the total of the non-sampled part of the  $m^{\text{th}}$  area;  $\overline{y}_m = \frac{y_m}{n_m}$ : the sample mean;  $f_m = \frac{n_m}{N_m}$ : the sampling rate;  $n_m$ : the sample size; and  $\widehat{\overline{Y}}_{mr}$ : a predictor for the mean of the non-sampled part of the  $m^{\text{th}}$  area. The predictor  $\widehat{Y}_{mr}$  can be derived from a LMM or Fay-Herriot model (see Fay and Herriot [7] (1979)).

### Hierarchical Bayesian (HB) Model

$$\log(y_{mk}) = \beta_1 + \beta_2 \log(x_{mk}) + u_m + \varepsilon_{mk}, \qquad (2.3)$$

where  $y_{mk}$  and  $x_{mk}$  are the number of full-time employees from the survey year and census year, respectively; m = 1, 2, ..., 29 denotes the  $m^{\text{th}}$  area;  $k = 1, 2, ..., N_m$ the  $k^{\text{th}}$  unit;  $u_m$  is the random effect of the  $m^{\text{th}}$  area,  $\varepsilon_{mk}$  is the error term. The log-transformation is applied to  $x_{mk}$  and  $y_{mk}$  to make the predictor and response variables approximately conform to normality. Then  $y_{mk}$  (m = 1, ..., M;  $k = n_m + 1, ..., N_m$ ) is predicted using the inverse transformation  $\hat{y}_{mk} = \exp(\hat{\beta}_1 + \hat{\beta}_2 \log(x_{mk}) + \hat{u}_m)$ .

# 2.1 HB model assuming normally distributed errors (*N*-model) given by (2.3), (2.4)-(2.5):

$$u_m | \tau^2 \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \tau^2),$$
 (2.4)

$$\varepsilon_{mk} | \sigma^2 \stackrel{\text{ind}}{\sim} \mathcal{N}(0, \sigma^2).$$
 (2.5)

#### MCMC specification for the *N*-model:

Parms: 
$$\beta_1 = 0, \ \beta_2 = 1, \ \tau^2 = 1, \ \sigma^2 = 1$$
 (2.6)

Priors: 
$$\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \sim \text{BVN}\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 50 & 0 \\ 0 & 50 \end{bmatrix}\right)$$
 (2.7)

$$\tau^2, \ \sigma^2 \sim \text{igamma}(0.01, \ 0.01)$$
 (2.8)

Random : 
$$u_m \sim \mathcal{N}(0, \tau^2)$$
 (2.9)

Likelihood : 
$$\log(y_{mk})|u_m \sim \mathcal{N}(\beta_1 + \beta_2 \log(x_{mk}) + u_m, \sigma^2)$$
 (2.10)

# 2.2 HB model with t-distributed errors (t-model) given by (2.3), (2.11)-(2.12):

$$u_m | \tau^2 \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \tau^2),$$
 (2.11)

$$\varepsilon_{mk} | \sigma^2 \stackrel{\text{iid}}{\sim} t(0, \sigma^2, \nu).$$
 (2.12)

### MCMC specification for the *t*-model:

Parms: 
$$\beta_1 = 0, \ \beta_2 = 1, \ \tau^2 = 1, \ \sigma^2 = 1$$
 (2.13)

Priors: 
$$\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \sim \text{BVN}\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 50 & 0 \\ 0 & 50 \end{bmatrix}\right)$$
 (2.14)

$$\tau^2, \ \sigma^2 \sim \text{igamma}(0.01, \ 0.01)$$
 (2.15)

Random : 
$$u_m \sim \mathcal{N}(0, \tau^2)$$
 (2.16)  
Likelihood :  $\log(y_{mk}) | u_m \sim t(\beta_1 + \beta_2 \log(x_{mk}) + u_m, \sigma^2, \nu = 4)$  (2.17)

# 2.3 HB model assuming error terms follow mixture of normal distributions (*MN*-model) given by (2.3), (2.18)-(2.20):

$$u_m | \tau^2 \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \tau^2),$$
 (2.18)

$$\varepsilon_{mk} | \sigma_1^2, \sigma_2^2, s_p \stackrel{\text{iid}}{\sim} (1 - s_p) \mathcal{N}(0, \sigma_1^2) + s_p \mathcal{N}(0, \sigma_2^2), \ \sigma_1 < \sigma_2, \tag{2.19}$$

$$s_p | p \stackrel{\text{no}}{\sim} \operatorname{Bin}(1; p).$$
 (2.20)

#### MCMC specification for the *MN*-model:

Parms: 
$$\beta_1 = 0, \ \beta_2 = 1, \ s_p = 0, \ \tau^2 = 0.01, \ \sigma_1^2 = 0.01, \ \sigma_2^2 = 1$$
 (2.21)

$$p = \frac{1}{1 + \exp(-s_p)}$$
(2.22)

Priors: 
$$\begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} \sim \text{BVN}\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 50 & 0 \\ 0 & 50 \end{bmatrix}\right)$$
 (2.23)

$$\tau^2, \ \sigma_1^2, \ \sigma_2^2 \sim \text{igamma}(0.01, \ 0.01)$$
 (2.24)

$$s_p \sim \operatorname{Bin}(1, p) \tag{2.25}$$

Random: 
$$u_m \sim \mathcal{N}(0, \tau^2)$$
 (2.26)

$$\mu = \beta_1 + \beta_2 \log(x_{mk}) + u_m, \ z_1 = \frac{\log(y_{mk}) - \mu}{\sigma_1}, \ z_2 = \frac{\log(y_{mk}) - \mu}{\sigma_2}$$

Likelihood : 
$$\log(y_{mk}) | u_m \sim \frac{p}{\sigma_1} \exp(-\frac{z_1^2}{2}) + \frac{1-p}{\sigma_2} \exp(-\frac{z_2^2}{2})$$
 (2.27)

Notice that, random effects are set up using random-effect distributions as specified in equations (2.9), (2.16), and (2.26). Non-informative priors (equations (2.7), (2.14), (2.23), (2.8), (2.15), (2.24)) would not influence the posterior distribution (see Ojo et al. [15] (2017) and Gelman [8] (2006)). The degree of freedom  $\nu = 4$  (equation (2.17)) is recommended in problems with small sampling rates (e.g. Lange et al. [11] (1989)). The MCMC procedures discard the first 2,500 as *burn-in* and keep the next 12,500 samples. The *thinning* rate of 5 is applied to produce 2,500 *thinned* samples from the posterior distribution. Then  $u_m$  is predicted by the average of MCMC posterior estimates of  $u_m$ .

## 3 Application to ASPEP data: MCMC Diagnostics and Test results

The ASPEP survey is designed to produce estimates of statistics on the number of federal, state, and local government civilian employees and their gross payroll for the month of March at the national level and for large domains. The target population of approximately 90,000 government units includes 5 types: counties, cities, townships, special districts, and school districts. The ASPEP consists of three components: a census of select federal agencies, a census of 50 state governments, and a sample of about 10,000 local governments. Every five years, in years ending in "2" and "7," the Census Bureau conducts a CoG. The employment component of the CoG, known as CoG-E, collects public employment and payroll data. About two years after every CoG-E, the Census Bureau redesigns and selects a new sample of local governments. The sample design is a two-phase, stratified, systematic probability-proportional-to-size design where the measure of size depends on total pay. See Dumbacher and Hill [6] (2014) for more details on the description of the sample design for the ASPEP.

To produce reliable estimates on the total number of full-time employees in government function codes where sampling rates are relatively small, we are exploring the Small Area Estimation (SAE) methodology that borrows strengths from previous census data instead of collecting expensive additional data for small cells (we refer the reader to Rao [16] (2003) for a comprehensive account on SAE techniques). Two recent consecutive censuses are used in this study, the 2007 and 2012 CoG-E..

The ASPEP data on employment include the number of full-time, part-time employees and gross pay as well as hours paid for part-time employees. The parameter of interest in this study is the total number of full-time employees,  $Y_m$ , for each function code m = 1, 2, ..., 29. We use samples from posterior distribution, produced by the MCMC procedure, to predict the total number of non-sampled full-time employees  $Y_{mr}$ . Then the estimate of the total number of full-time employees for the  $m^{\text{th}}$  area would be  $\hat{Y}_m = y_m + \hat{Y}_{mr}$ .

The convergence of the MCMC procedures can be assessed from Figures D1, D2, D3, D4, D5. The traceplots, of the *drawn value* of the parameters at each iteration against the number of MCMC iterations, all show good mixing of Markov chains. Samples from the posterior distribution can then be used to estimate the non-sampled total number of full-time employees for each function code.

The quality of the estimators is evaluated using the Relative Root Mean Square Error: RRMSE =  $\sqrt{\frac{1}{\text{rep}}\sum_{i=1}^{\text{rep}}(\frac{\widehat{Y}_{m,i}-Y_m}{Y_m})^2}$  where  $\widehat{Y}_{m,i}$  is an estimate of  $Y_m$ , rep = 1,000 is the number of replicate ASPEP samples selected from 2007 CoG data and used to estimate totals for 2012.

Let  $\operatorname{RRMSE}_N$ ,  $\operatorname{RRMSE}_T$ , and  $\operatorname{RRMSE}_{MN}$  (last three columns in each Table) be the RRMSEs of the HB estimates using normal, t, and mixture of normal distributions respectively. The following five tables show test results as applied to the ASPEP data of the states of Alabama, California, Georgia, Illinois, and Louisiana:

3.1 Application to Alabama ASPEP data - MCMC convergence diagnostics for  $\theta = (\beta_1, \beta_2, \tau^2, \sigma_1^2, \sigma_2^2)$  and comparison of RRMSEs of the estimates







Data Source: U.S. Census Bureau 2007 and 2012 Census of Government - Employment

Figure T1a indicates the N-model is the least efficient. Figure T1b suggests the MN-model is the most efficient. Figure T1c shows that, on the average, the MN-model provides HB estimates with smallest RRMSEs and estimates using N-model have largest RRMSEs.

3.2 Application to California ASPEP data - MCMC convergence diagnostics for  $\theta = (\beta_1, \beta_2, \tau^2, \sigma_1^2, \sigma_2^2)$  and comparison of RRMSEs of the estimates







Data Source: U.S. Census Bureau 2007 and 2012 Census of Government - Employment

Figure T2a indicates the N-model is the least efficient. Figure T2b suggests the MN-model is the most efficient. Figure T2c shows that, on the average, the MN-model provides HB estimates with smallest RRMSEs and estimates using N-model have largest RRMSEs.

3.3 Application to Georgia ASPEP data - MCMC convergence diagnostics for  $\theta = (\beta_1, \beta_2, \tau^2, \sigma_1^2, \sigma_2^2)$  and comparison of RRMSEs of the estimates







Data Source: U.S. Census Bureau 2007 and 2012 Census of Government - Employment

Figure T3a indicates the N-model is the least efficient. Figure T3b suggests the MN-model is the most efficient. Figure T3c shows that, on the average, the MN-model provides HB estimates with smallest RRMSEs and estimates using N-model have largest RRMSEs.

3.4 Application to Illinois ASPEP data - MCMC convergence diagnostics for  $\theta = (\beta_1, \beta_2, \tau^2, \sigma_1^2, \sigma_2^2)$  and comparison of RRMSEs of the estimates







Data Source: U.S. Census Bureau 2007 and 2012 Census of Government - Employment

Figure T4a indicates the N-model is the least efficient. Figure T4b suggests the MN-model is the most efficient. Figure T4c shows that, on the average, the MN-model provides HB estimates with smallest RRMSEs and estimates using N-model have largest RRMSEs.

3.5 Application to Louisiana ASPEP data - MCMC convergence diagnostics for  $\theta = (\beta_1, \beta_2, \tau^2, \sigma_1^2, \sigma_2^2)$  and comparison of RRMSEs of the estimates







Figure T5a indicates the N-model is the least efficient. Figure T5b suggests the MN-model is the most efficient. Figure T5c shows that, on the average, the MN-model provides HB estimates with smallest RRMSEs and estimates using N-model have largest RRMSEs.

## 3.6 Conclusions

On the average, the MN-model provides HB estimates with smallest RRMSEs, estimates using N-model have largest RRMSEs. The N-model is the least efficient. The MN-model is the most efficient.

The performance of the estimators using the t or the mixture of normal distributions is significantly more reliable than the one using normal distribution. The mixture of normal model is better than the t-model in terms of RRMSE. Our future projects may focus on models using mixture of t-distributions or finite mixture of normal distributions with more than two mixing components.

## Appendix

FC	Description
001	Air Transportation
005	Correction
012	Elementary and Secondary - Instruction
016	Higher Education - Other
018	Higher Education - Instructional
023	Financial Administration
024	Firefighters
025	Judicial & Legal
029	Other Government Administration
032	Health
040	Hospitals
044	Highways
050	Housing & Community Development
052	Libraries
059	Natural Resources
061	Parks & Recreation
062	Police Protection - Officers
079	Public Welfare
080	Sewerage
081	Solid Waste Management
087	Water Transport & Terminals
089	All Other & Unallocable
091	Water Supply
092	Electric Power
093	Gas Supply
094	Transit
112	Elementary & Secondary Schools - Other
124	Fire - Other
162	Police - Other

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