

On Superiority of Adaptive Sequential Designs

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Prelude

Statistical Inference

- a game with two players
 - one player is *nature*
 - the other player is *the statistician*
- unknown true state of nature
- experiments
- random chance

Two Strategies

- static designs
 - correct assumption or loss of power
- adaptive designs
 - best assumption with the flexibility to modify

Intuition

Adaptive designs are superior

Motivation

Group Sequential Designs

- Armitage, McPherson and Rowe (1969)
- large body of literature

Unavoidable Difficulty

- low conditional power

Sample Size Adjustment

- the observed effect

Lack of Efficiency

- Tsiatis and Mehta (2002)
- Jennison and Turnbull (2003)

Better Efficiency and Effectiveness

- a minimum effect size (Liu and Chi, 2001)

Two-Stage Designs

Hypothesis

$H_0 : \delta \leq 0$ in favor of $H_1 : \delta > 0$ with a minimum effect size δ_{\min}

Procedure

Assume observations from two distinct stages are independent, for which p_1 and p_2 are the 1st and 2nd stage p -values against H_0

- specify $\alpha_1 < \alpha < \alpha_1^*$, $\beta_1^* < \beta$, and a conditional error function $A(p_1)$ such that
 - $P_{\delta_{\min}}\{p_1 \leq \alpha_1^*\} = 1 - \beta_1^*$
 - $\alpha_1 + \int_{\alpha_1}^{\alpha_1^*} A(p_1) dp_1 = \alpha$
- reject H_0 if $p_1 \leq \alpha_1$; accept H_0 if $p_1 > \alpha_1^*$; continue, otherwise
- reject H_0 if $p_2 \leq A(p_1)$

Validity

Type I error rate is controlled if p_1 and p_2 are independent

Two-Stage Designs

Example 1

Two-stage group sequential designs

- fixed second stage sample size n_2
- p_1 and p_2 are independent
- $A(p_1) = 1 - \Phi\{\mu - \gamma\Phi^{-1}(1 - p_1)\}$
 - $\Phi(\cdot)$ is the cdf of the standard normal distribution
 - $\gamma = \{w/(1 - w)\}^{1/2}$ where w is the information fraction
 - μ is calculated to satisfy

$$\alpha_1 + \int_{\alpha_1}^{\alpha_1^*} A(p_1) dp_1 = \alpha$$

Example 2

Two-stage adaptive designs where

$$n_2 = n_2(p_1)$$

Two-Stage Adaptive Designs

Notion of Adaptation

Formalization of the process for

- interim analysis
- decision making on modifications
- assessing the final trial outcomes

Three basic components

- interim data
- adaptation rule
- final trial outcome

Notations

- interim data X_* and full data X
- a countable set M of modifications
- adaptation rule $g : X_* \longrightarrow M$
- a procedure $p_m(X)$ for each $m \in M$
- the adaptive procedure $p_g = p_{g(X_*)}(X)$

Two-Stage Adaptive Designs

Stochastic Independence

Let $X = (X_*, X^*)$ where X_* and X^* are independent. Consider

- $g = g(X_*)$
 - $p_1 = p_1(X_*)$
 - $p_{2m} = p_{2m}(X^*)$ for each $m \in M$
 - $p_2 = p_{2g}$
- i) (g, p_2) is independent of p_1 iff g and p_1 are independent, or
- ii) (g, p_1) is independent of p_2 iff p_{2m} follow the same distribution for all $m \in M$

Application

Sample size adjustment (Liu and Chi, 2001)

$$g = n_2(p_1) = \{z_{A(p_1)} + z_{\beta_2}\}^2 / \delta_{\min}^2$$

where

- $\beta_2 = (\beta - \beta_1^*) / (\beta_1 - \beta_1^*)$
- $\beta_1 = P_{\delta_{\min}}\{p_1 > \alpha_1\}$

Efficiency

Assumptions

- same n_1 and α_1 , and therefore, $1 - \beta_1$
- same $1 - \beta$

Notations

- d for design
- $N_d(\delta)$ for average sample size
- Thall, Simon and Ellenberg (1988)
 - π for probability that $\delta = \delta_m$
 - $1 - \pi$ for probability that $\delta = 0$
- $\mathcal{N}_d(\pi) = \pi N_d(\delta_m) + (1 - \pi)N_d(0)$

Definition

Design d_2 is more efficient than design d_1 if and only if $\mathcal{N}_{d_2}(\pi) \leq \mathcal{N}_{d_1}(\pi)$

Effectiveness

Notations

- $C(n)$ for cost of experimentation, increasing in n
- $S(n)$ for payoff in future for rejecting H_0 , decreasing in n

Benefit

$$\begin{aligned} & B_d(\delta) \\ = & [\{S(n_1) - C(n_1)\}P_1 - C(n_1)Q_1] \\ & + \int_{\alpha_1^*}^{\alpha_1^*} \{S(n_1 + n_2)P_2 - C(n_1 + n_2)\}f_\delta(p_1)dp_1 \end{aligned}$$

where

- $P_1 = P_\delta\{p_1 \leq \alpha_1\}$
- $Q_1 = P_\delta\{p_1 > \alpha_1^*\}$
- $n_2 = n_2(p_1)$
- $P_2 = P_\delta\{p_2 \leq A(p_1) \mid p_1\}$
- $f_\delta(p_1)$ for density of p_1

Risk

$$R_d(\delta) = C(n_1) + \int_{\alpha_1}^{\alpha_1^*} C(n_1 + n_2)f_\delta(p_1)dp_1$$

Effectiveness

Definition

Design d_2 is more effective than design d_1 if and only if

- i) $R_{d_2}(\delta) \leq R_{d_1}(\delta)$ for $\delta \geq \delta_{\min}$, and
- ii) $B_{d_2}(\delta) \geq B_{d_1}(\delta)$ for $\delta \geq \delta_{\min}$

Incremental Risk Benefit Ratio

$$\begin{aligned} & IRBR(\delta) \\ &= \{R_{d_2}(\delta) - R_{d_1}(\delta)\} / \{B_{d_2}(\delta) - B_{d_1}(\delta)\} \end{aligned}$$

Alternative Formulations

- $B_d(\delta)$ in health outcomes, and $R_d(\delta)$ in monetary cost
- $B_d(\delta)$ and $R_d(\delta)$ both in health outcomes
- $B_d(\delta)$ and $R_d(\delta)$ in personal benefit and loss

Numerical Example

Clinical Trial

- double-blind parallel study to compare an experimental drug to a placebo
- response to treatment, success or failure
- response rate of the drug $r_2 = 0.5$
- response rate of the placebo $r_1 = 0.35$ but higher rate $r_1 = 0.4$ possible
- $\pi = 0.5$

Benefit-Risk Considerations

- $C(n) = 2 + 0.05n$
- $S(n) = 10(120 - 12 - n/30)$

Test Statistic and Effect Size

- $T = (2n)^{1/2} \{ \arcsin(\hat{r}_2^{1/2}) - \arcsin(\hat{r}_1^{1/2}) \}$
- $\delta = (2)^{1/2} \{ \arcsin(r_2^{1/2}) - \arcsin(r_1^{1/2}) \}$
- $\delta_{\min} = 0.1424$

Numerical Example

Common Design Features

- $\alpha = 0.025, \beta = 0.05$
- $w = 0.5$
- $\alpha_1 = 0.00153$ by O'Brien-Fleming α -spending function
- $n_1 = 338$ per group
- $1 - \beta_1 = 0.3648$

Comparison of Designs

	d_{gs}	d_{a_1}	d_{a_2}
β_1^*	0.02159	0.02946	0.02938
α_1^*	0.27595	0.23329	0.23365
$\mathcal{N}_d(\pi)$	487.81	491.70	470.76
$B_d(\delta_{\min})$	823.87	831.07	836.40
$R_d(\delta_{\min})$	29.26	28.17	27.46

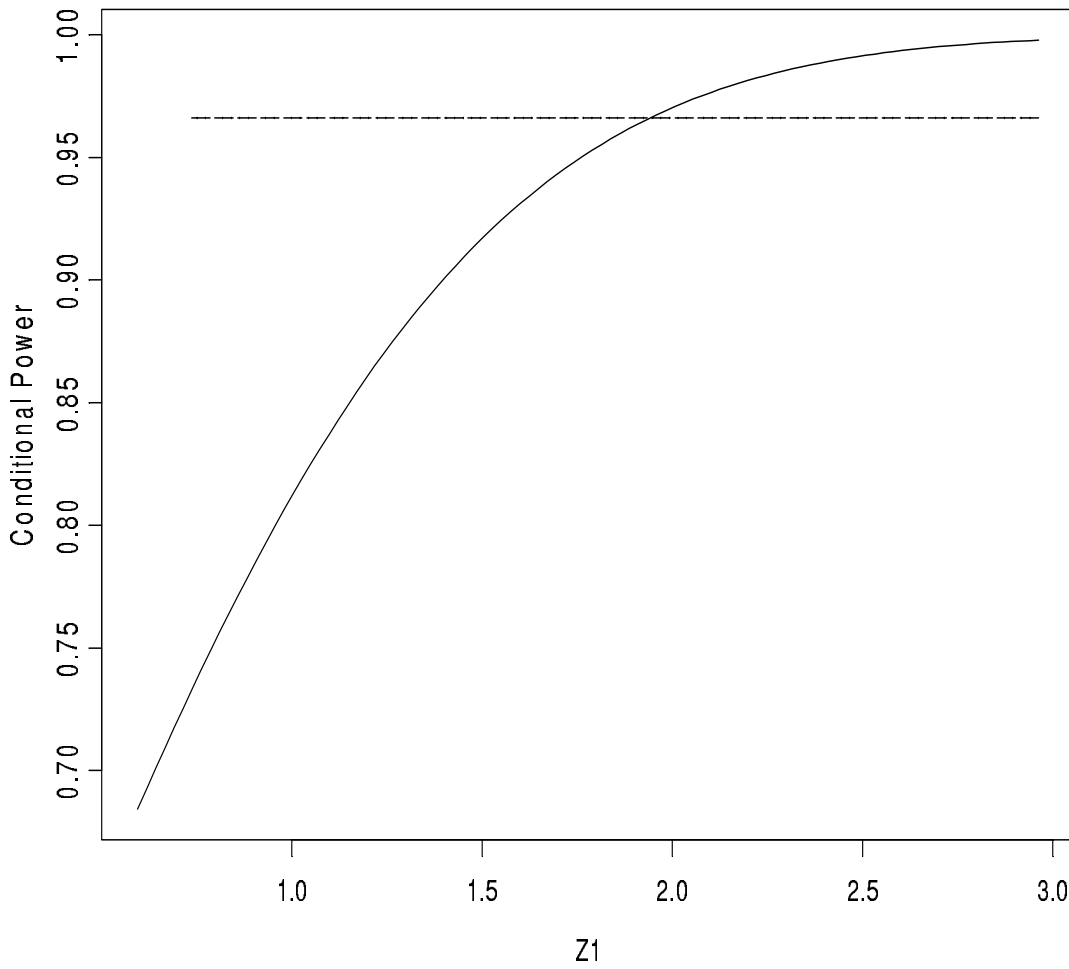
d_{gs} — two-stage group sequential design

d_{a_1} — two-stage adaptive design

d_{a_2} — adaptive design with upto three stages

Numerical Example

Conditional Power

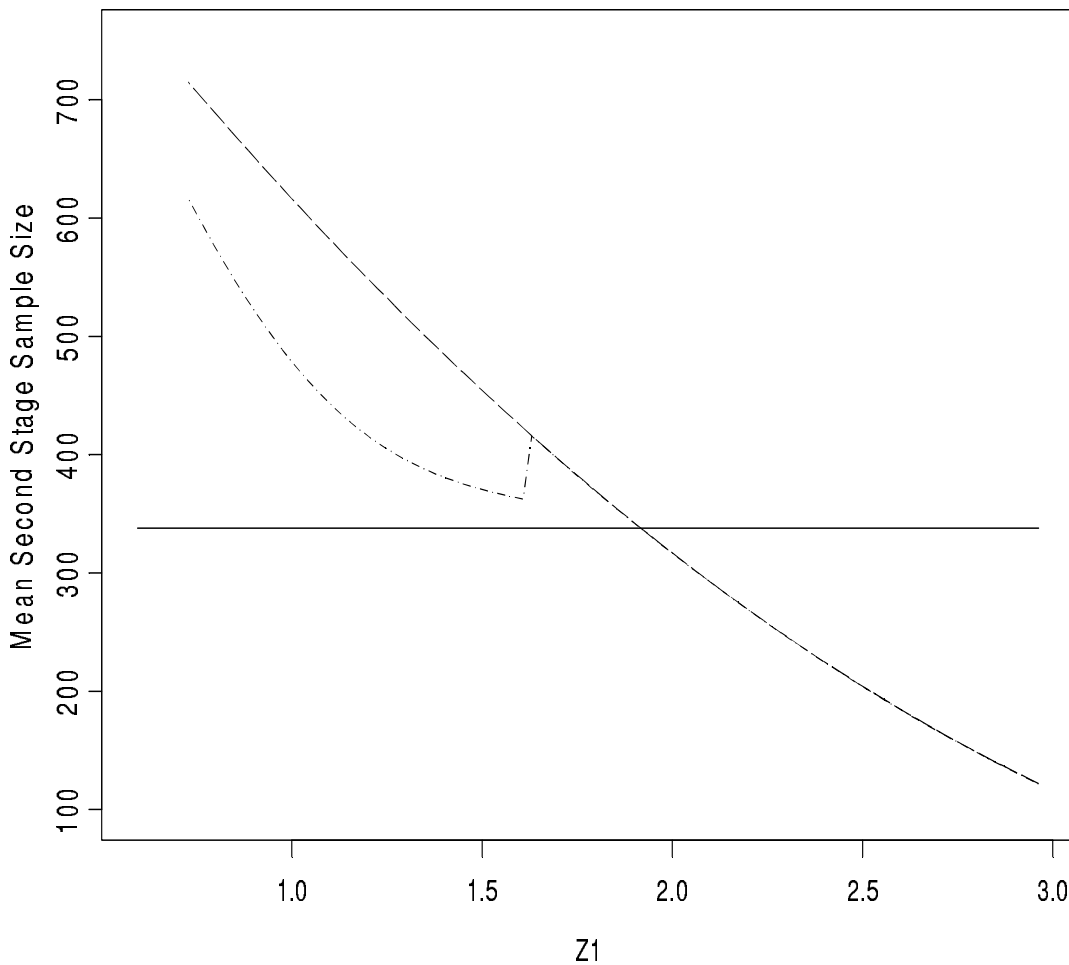


solid — d_{gs}

dash — d_{a_1} and d_{a_2}

Numerical Example

Mean Second Stage Sample Size



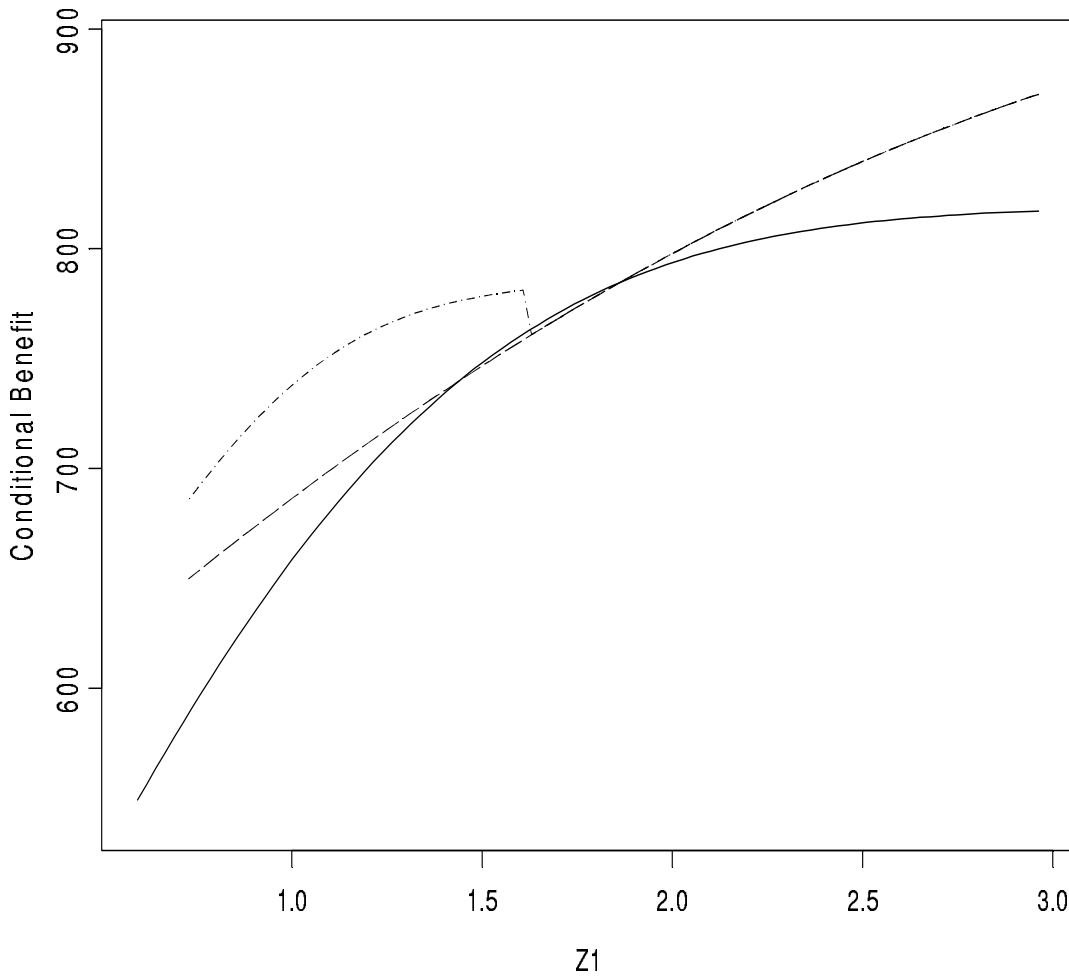
solid — d_{gs}

dash — d_{a_1}

dot-dash — d_{a_2}

Numerical Example

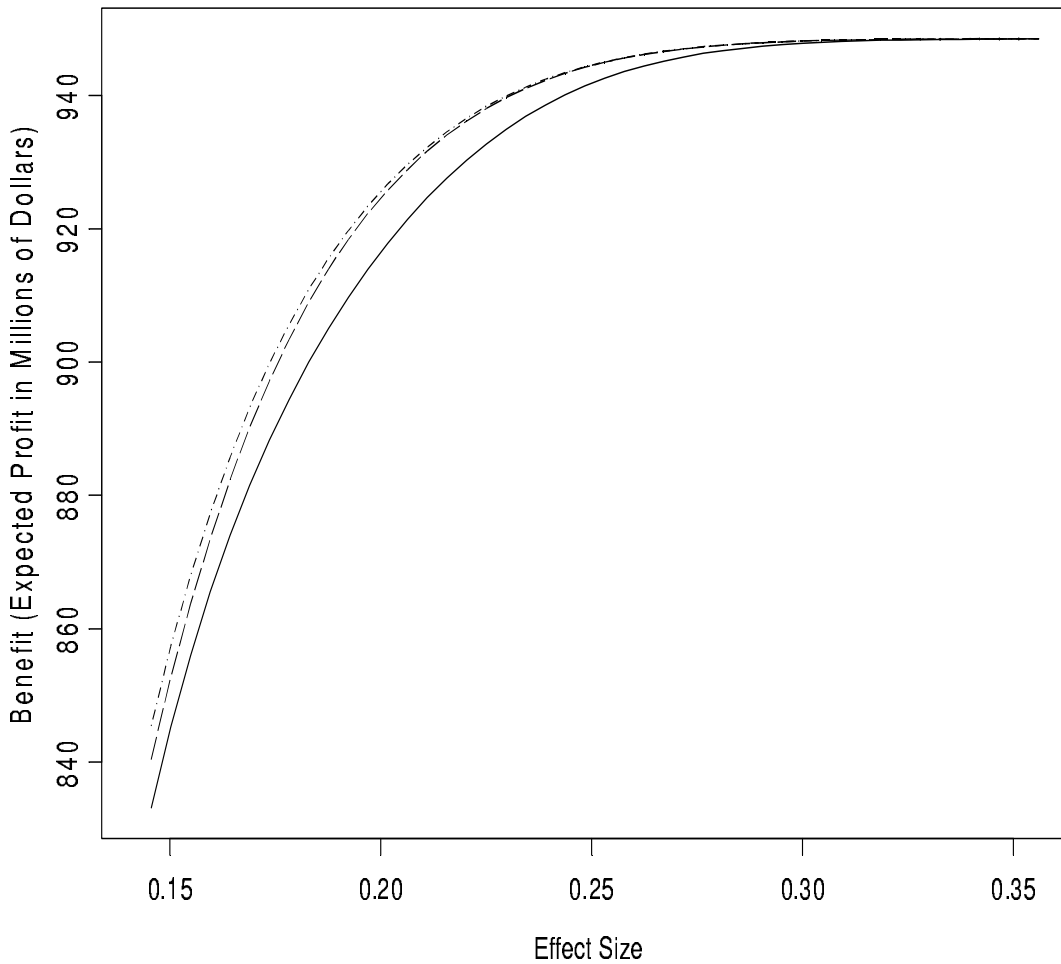
Conditional Benefit



solid — d_{gs}
dash — d_{a_1}
dot-dash — d_{a_2}

Numerical Example

Benefit Function



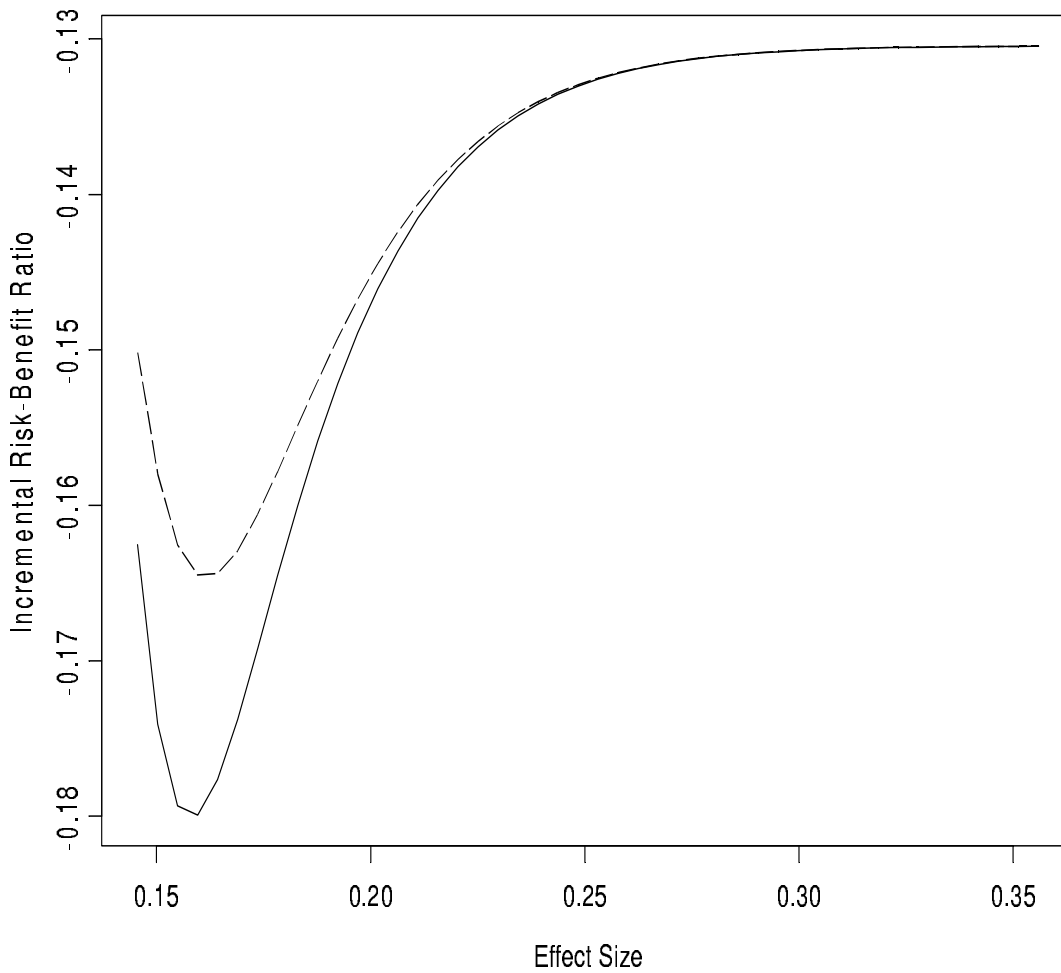
solid — d_{gs}

dash — d_{a_1}

dot-dash — d_{a_2}

Numerical Example

IRBR



solid — d_{a_1} against d_{gs}

dash — d_{a_2} against d_{gs}

Discussion

Sample Size Adjustment

- adaptive designs can be more efficient and effective by allowing sample size increase
- adaptive designs can be more efficient and effective without sample size increase
- extended UMP criteria of Tsiatis and Mehta (2002) are problematic
- sufficiency is no guarantee of optimality

Other Adaptations

- dose or regimen selection
- change or selection of endpoints
- improvement of statistical analysis

New Clinical Development Paradigm

- phase 2/3 combination designs
- accelerated approval of life-saving drugs