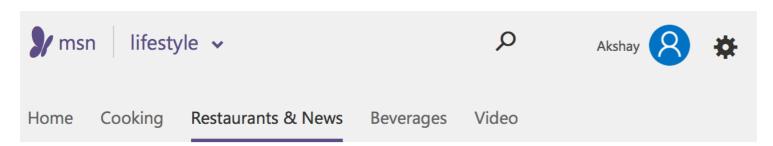
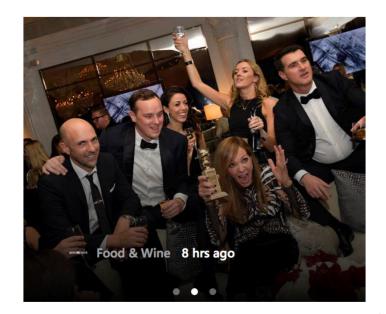
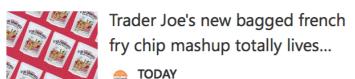
Online and Offline Experimentation in Complex Systems

Akshay Krishnamurthy Microsoft Research, NYC <u>akshay@cs.umass.edu</u>



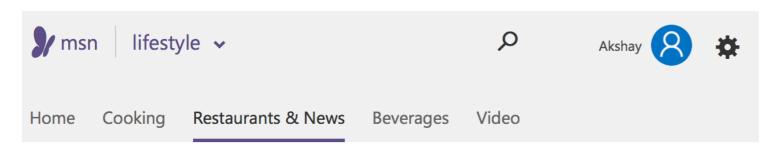


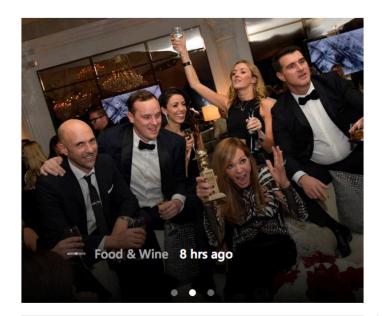


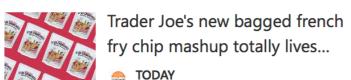




Learn from interacting with users in production



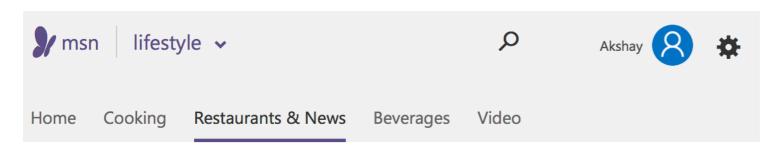


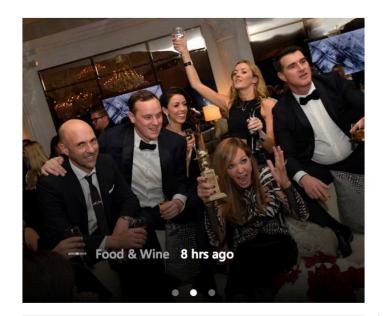


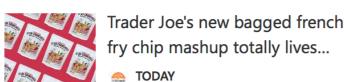




- Learn from interacting with users in production
- No counterfactuals



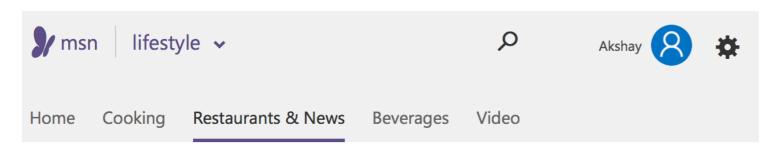


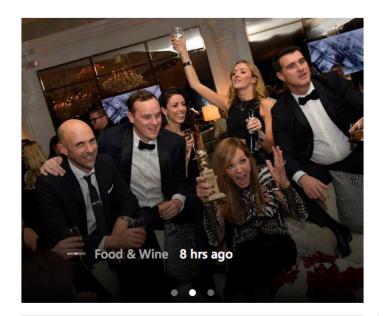


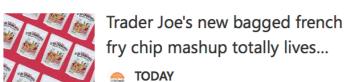




- Learn from interacting with users in production
- No counterfactuals
- Exploration vs Exploitation



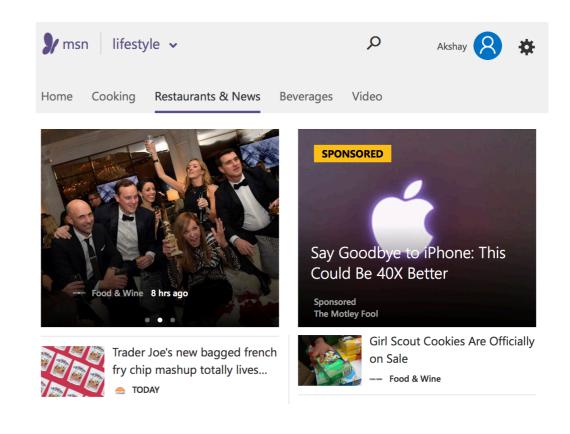






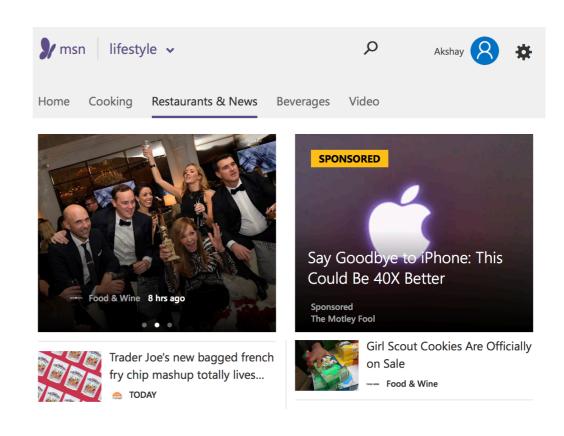


- Learn from interacting with users in production
- No counterfactuals
- Exploration vs Exploitation
- Optimize whole-page layout



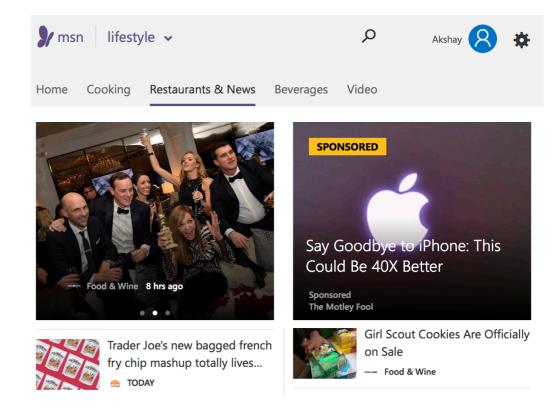
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- 1. Use π for 1/2 of traffic (at random)
- 2. Evaluate π 's quality (click prob.)



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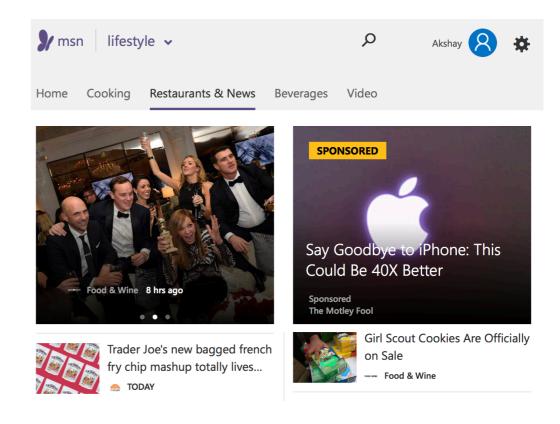
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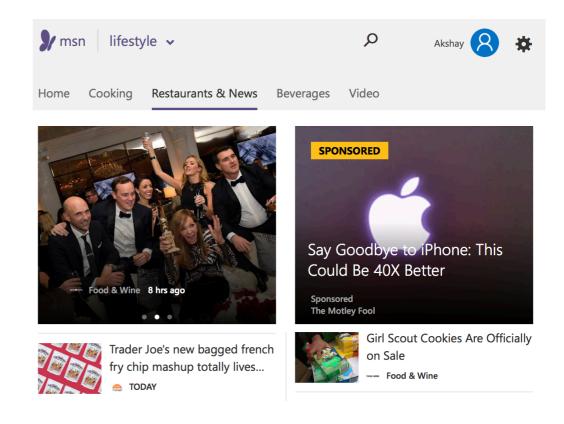


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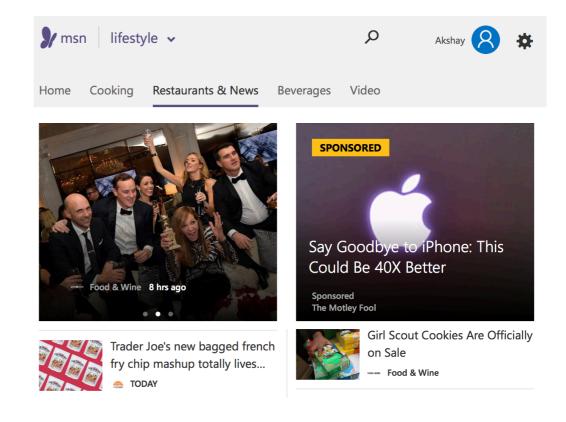


Two main issues:

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- 2. Requires $O(|\Pi|)$ samples to evaluate $|\Pi|$ policies

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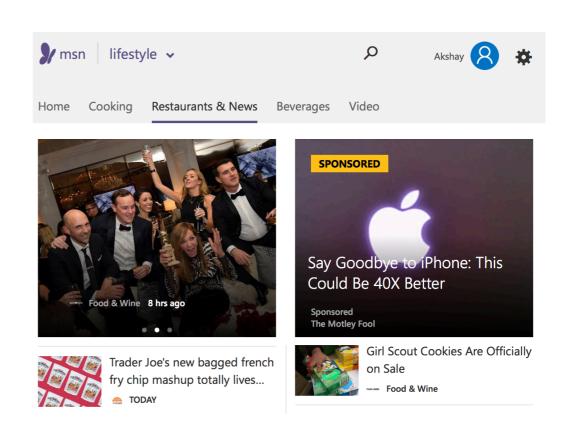
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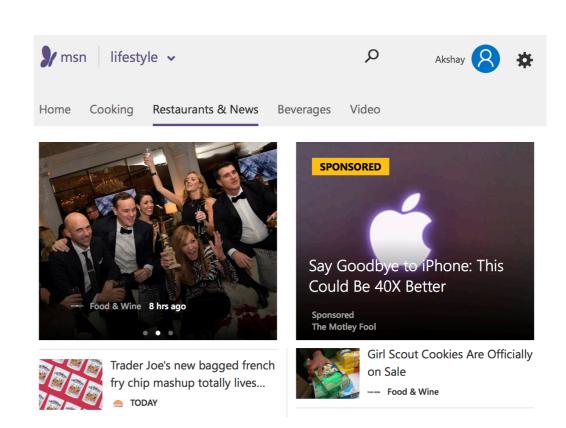
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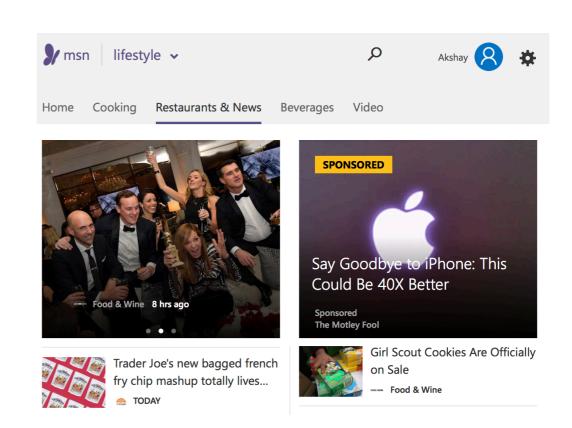
Can do exponentially better with contextual bandits!



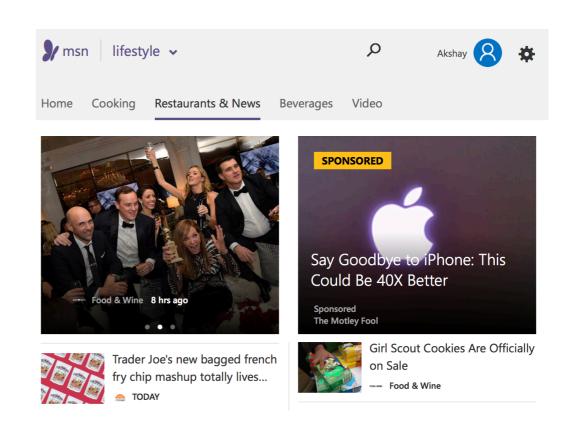
 Collect dataset by serving content at random



- Collect dataset by serving content at random
- For each policy, estimate
 performance by taking
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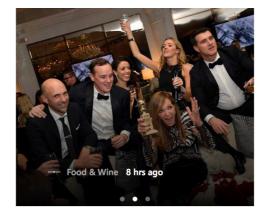


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With K actions and $|\Pi|$ policies, we need $O(K\log|\Pi|)$ samples



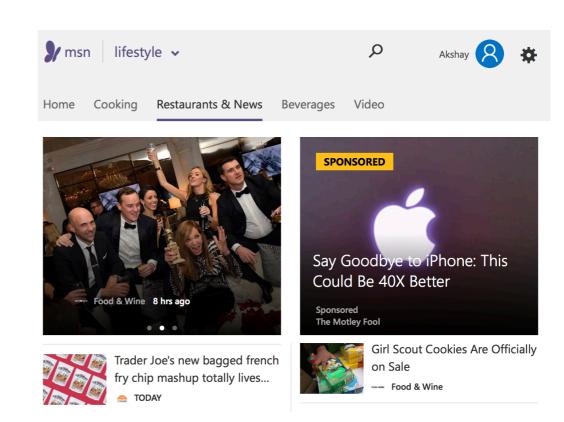




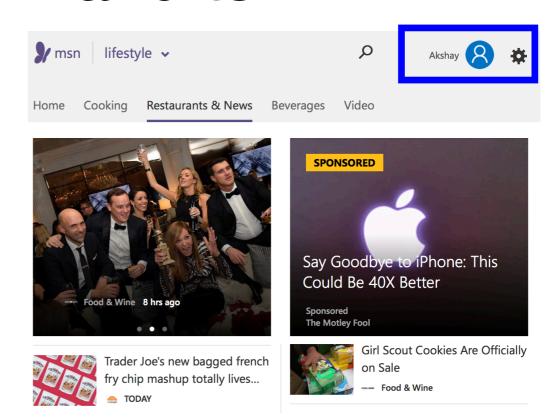




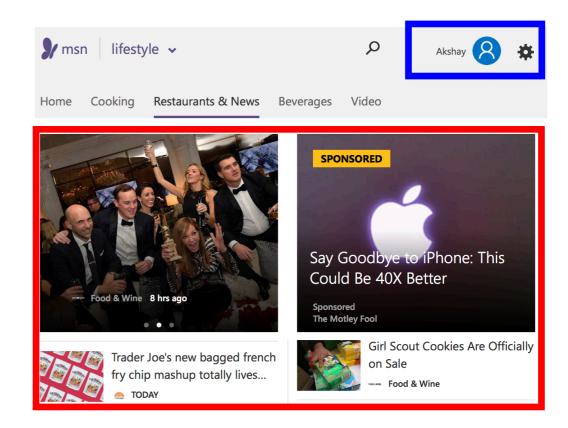
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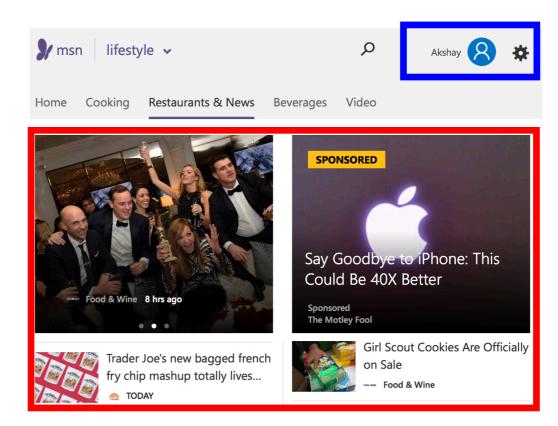
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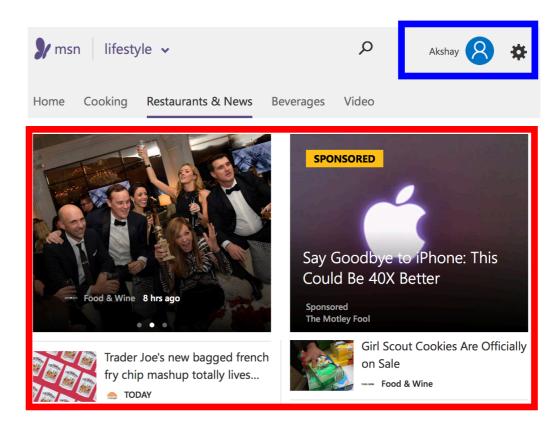


$$r_t = \# \text{ clicks}$$

On each of T rounds:

- 1. Observe context x_t
- 2.Play action a_t
- 3. Observe reward $r_t(a_t, x_t)$

K = number of actions

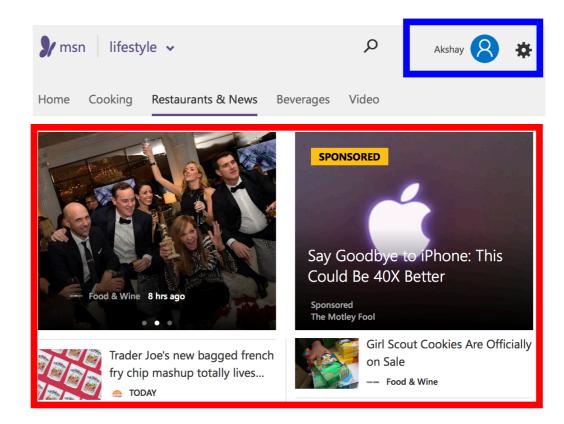


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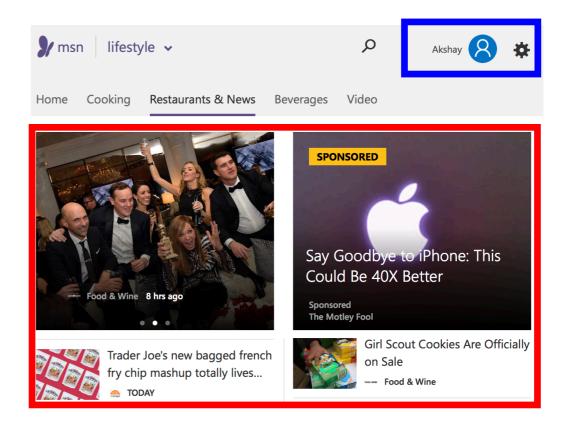
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$$\operatorname{Regret}(T,\Pi) = \max_{\pi \in \Pi} \operatorname{Reward}(T,\pi) - \operatorname{LearnerReward}(T)$$

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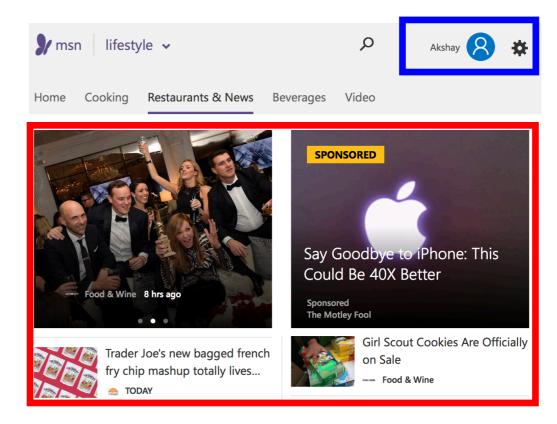
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Fact: Can get $\sqrt{KT\log |\Pi|}$ regret.

On each of T rounds:

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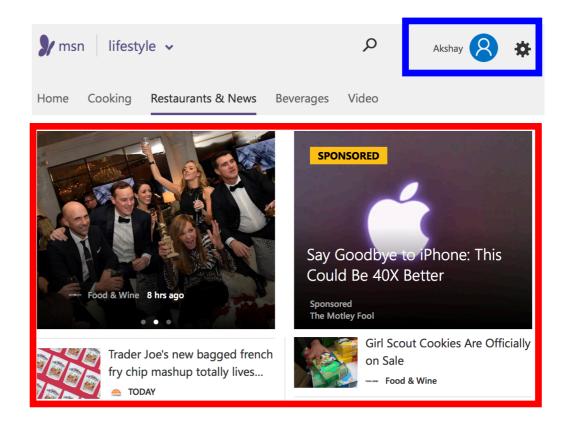
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A/B testing gets $(|\Pi|)^{1/3}T^{2/3}$ Fact: Can get $\sqrt{KT\log|\Pi|}$ regret. Offline Eval gets $(K\log|\Pi|)^{1/3}T^{2/3}$

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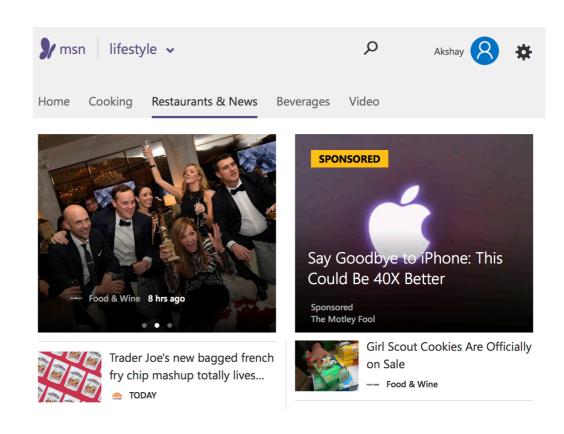


$$r_t = \# \text{ clicks}$$

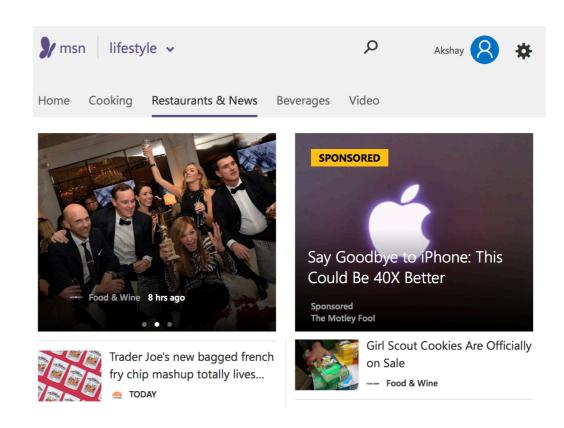
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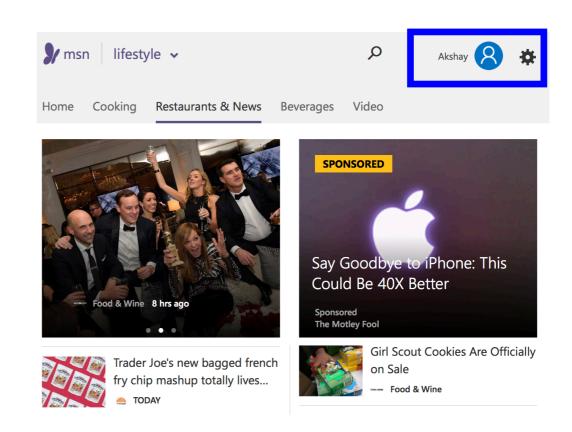
Exponential with combinatorial action space!



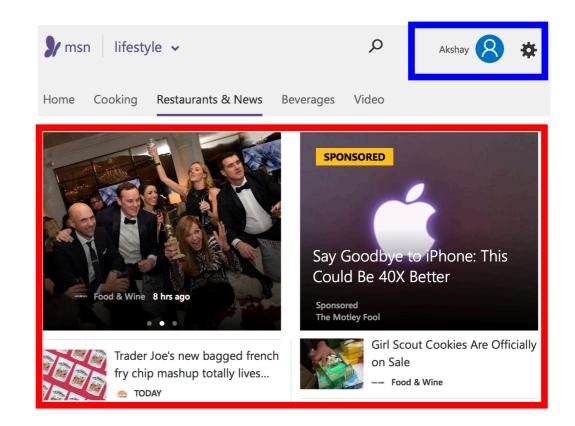
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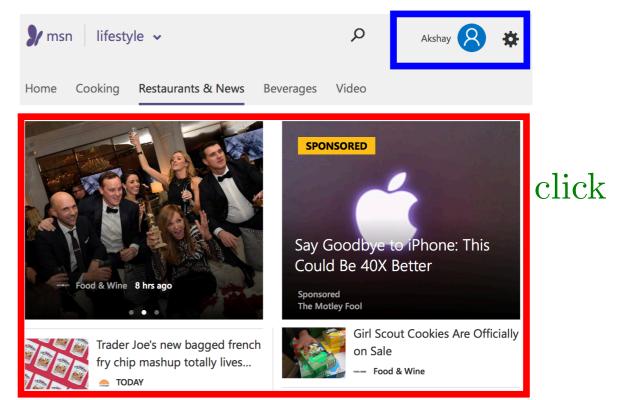


- 1. Observe context x_t
- 2.Play action $A_t = (a_1, \dots, a_L)$
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On each of T rounds:

- 1. Observe context x_t
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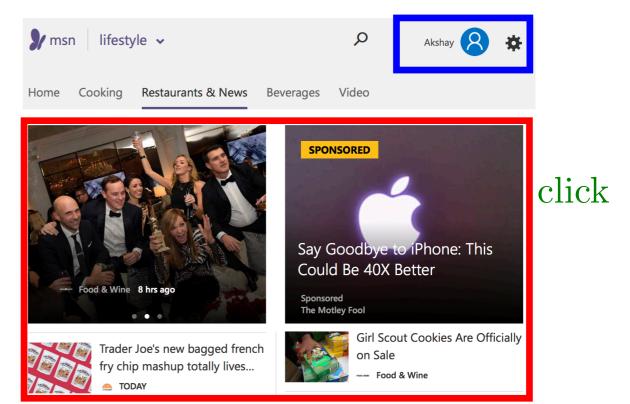


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$$r_t(A_t, x_t) = \sum_{\ell} y(a_{\ell}) + \text{noise}$$



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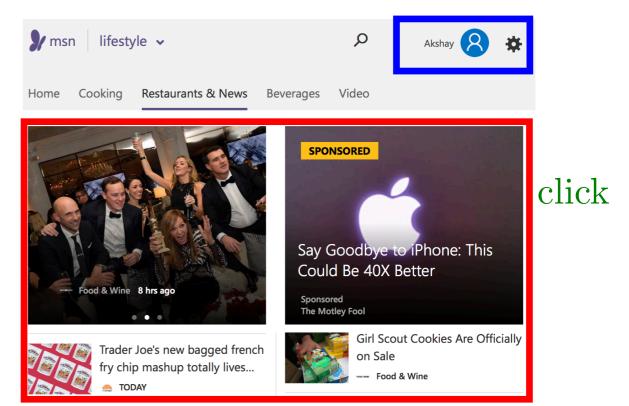
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B = number of simple actions

L = composite action length



click

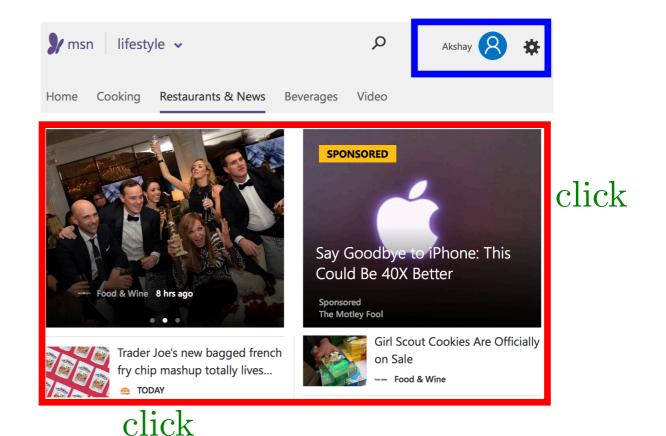
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Question: Improve performance by leveraging reward structure + additional feedback?

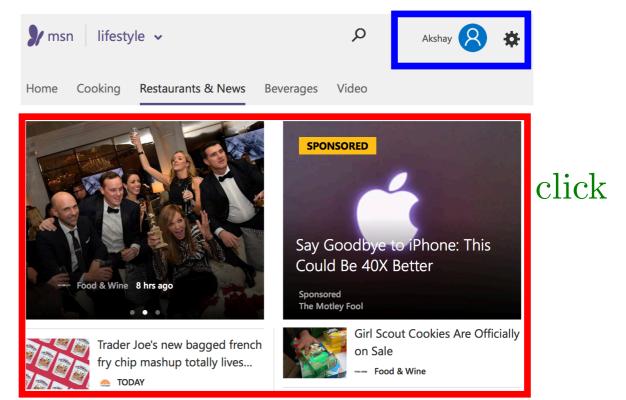
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click

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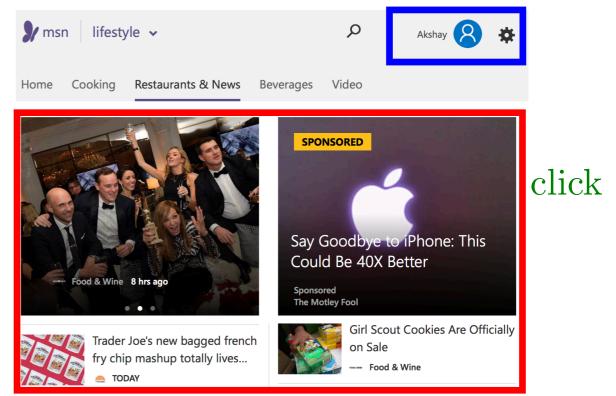
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click

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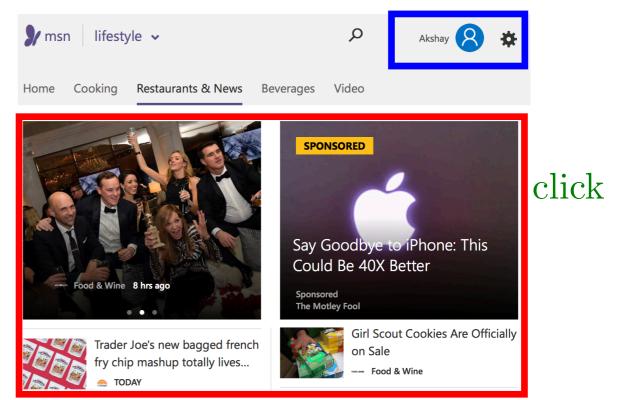
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- Off-policy evaluation?
- Explore vs Exploit?

Contextual Semibandits

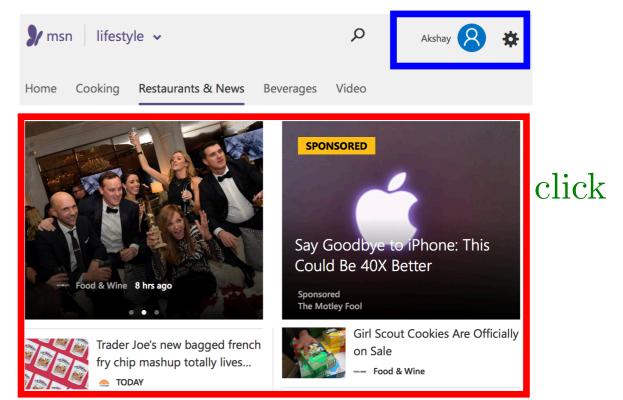
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click

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- Off-policy evaluation?
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- Computational Efficiency?

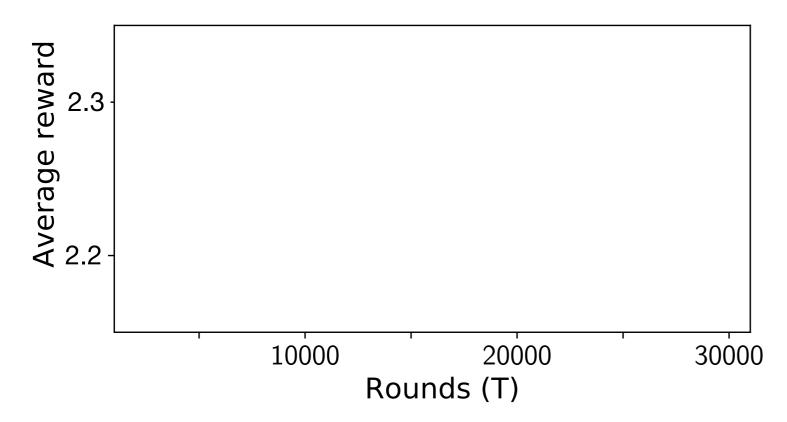
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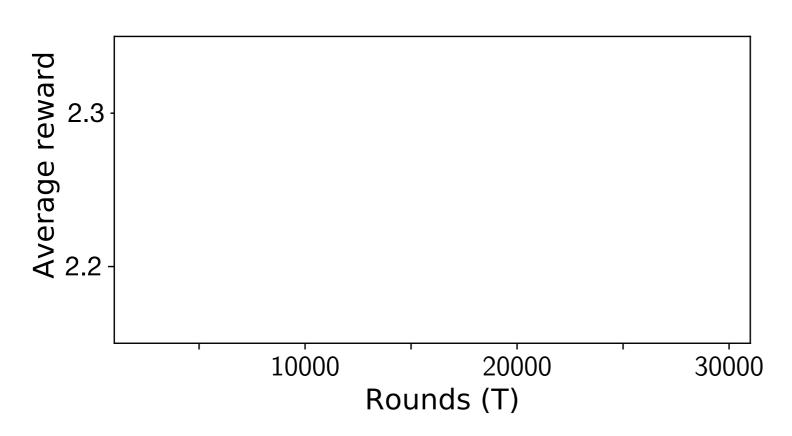


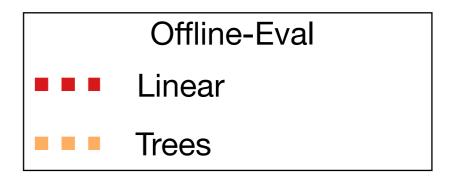
[Krishnamurthy, Agarwal, Dudik. NeurIPS 2016]

Theorem: Efficient algorithm with $\sqrt{BT \log(|\Pi|)}$ regret

Parameters: T rounds, B simple actions, composite action length L

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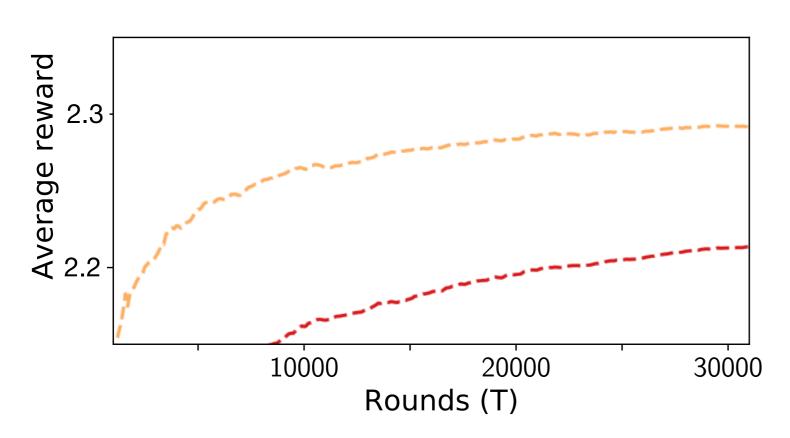


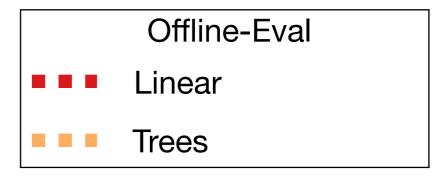


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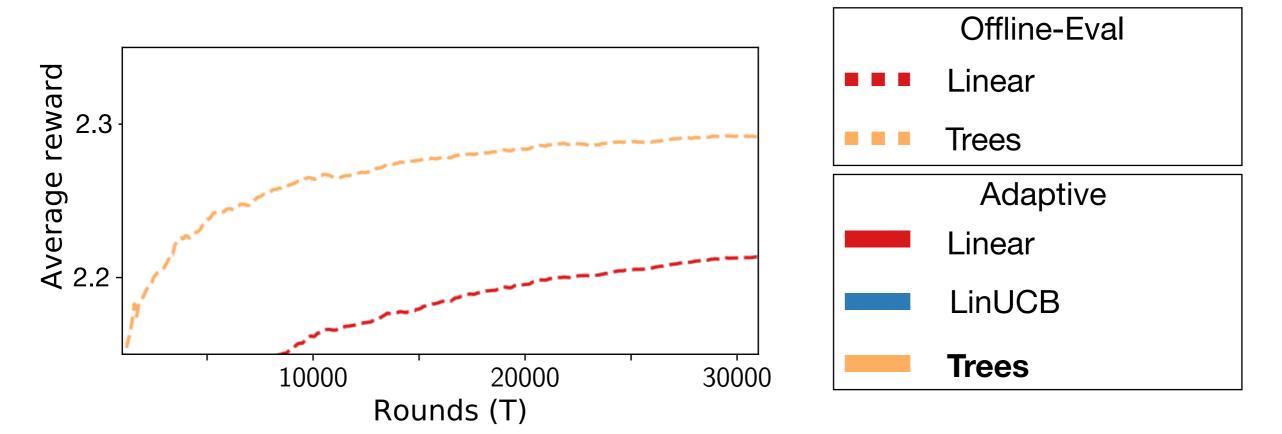




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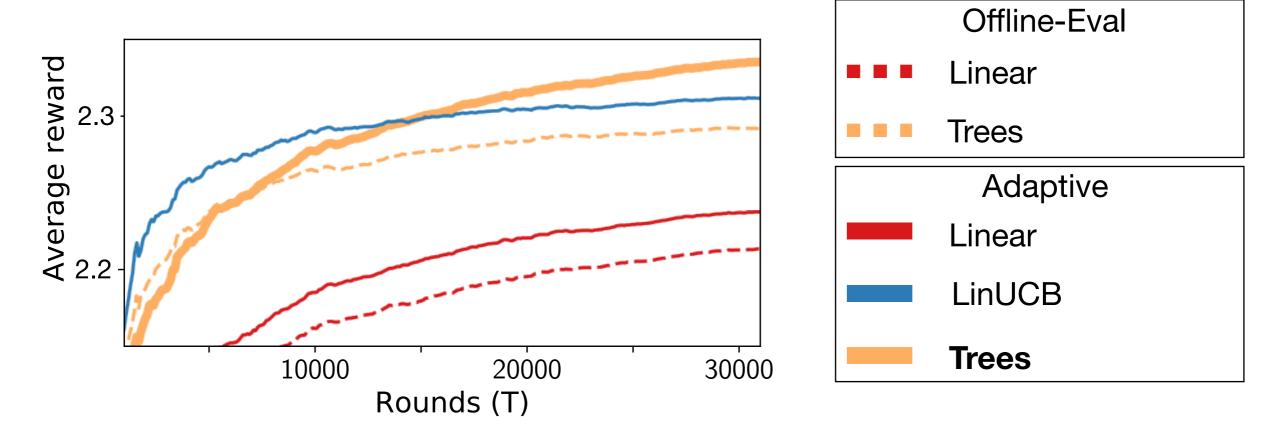
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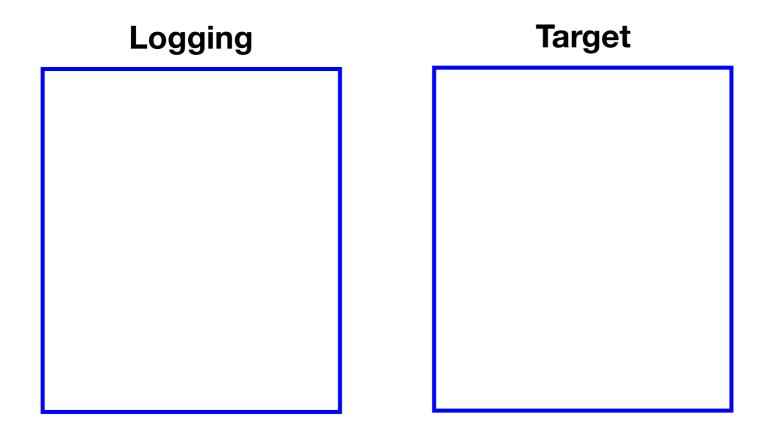
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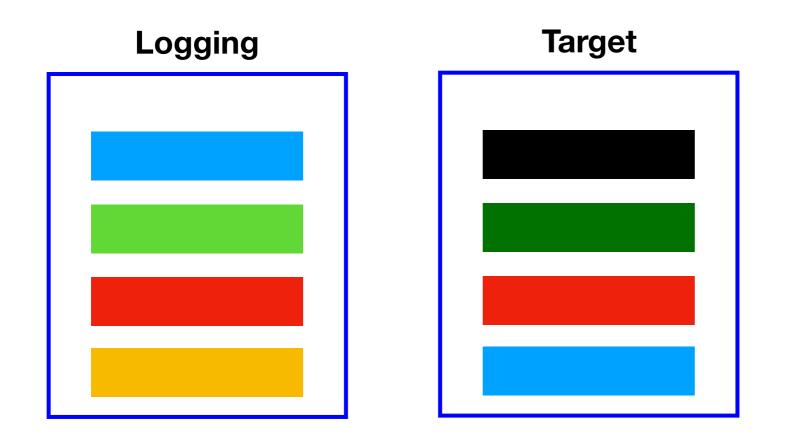
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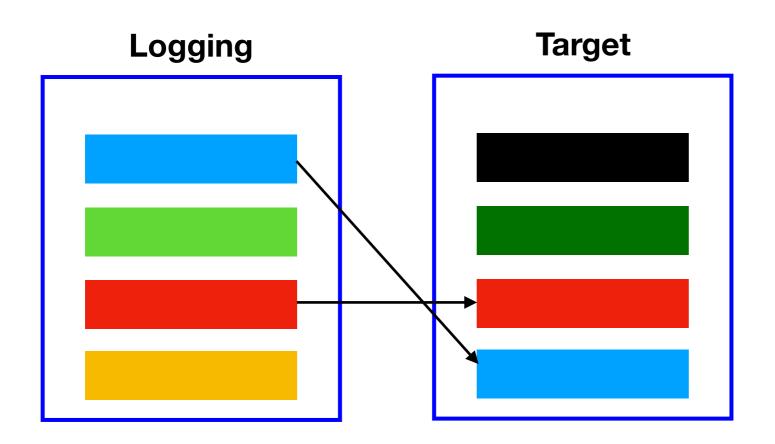
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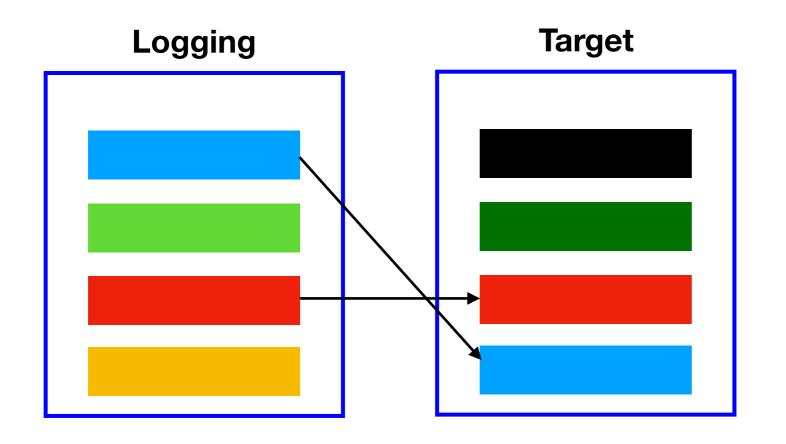
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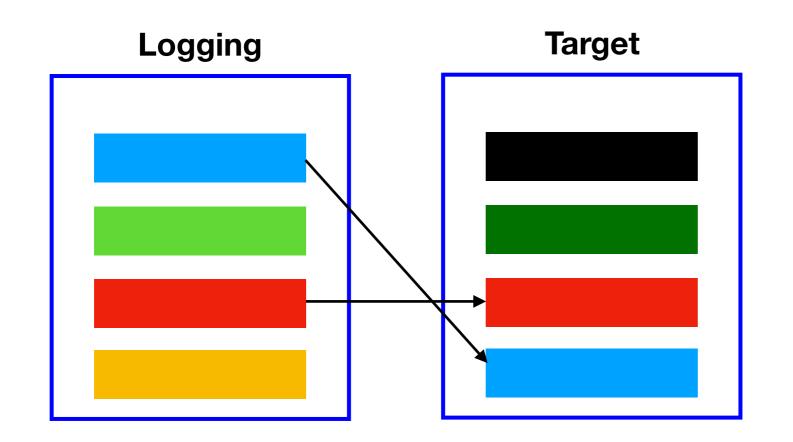


Subproblem: Given data collected by a logging policy, estimate reward of a target policy



Idea: Use partial matches!

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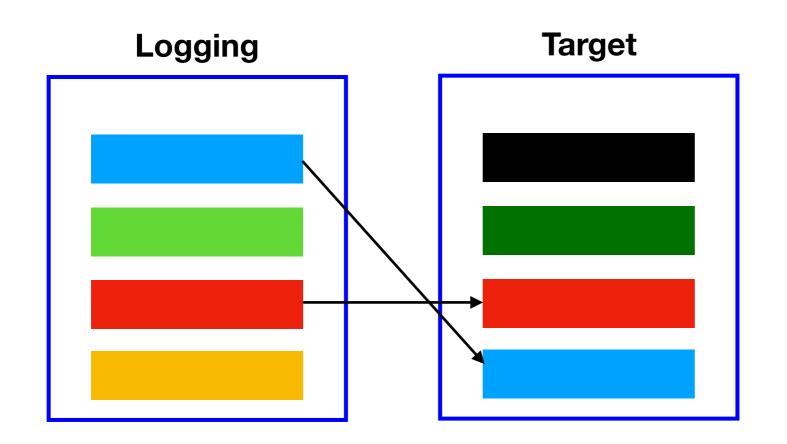
Idea: Use partial matches!

If
$$A \sim Q(\cdot|x)$$

$$\hat{y}(a) = \frac{y(a)\mathbf{1}(a \in A)}{Q(a \in A|x)}$$

$$\hat{r}(\pi, x) = \sum_{a \in \pi(x)} \hat{y}(a)$$

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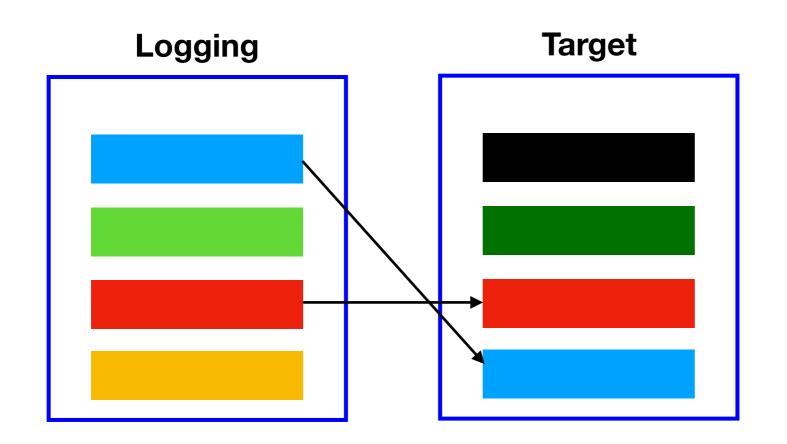
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Uniform Q gives O(B) variance

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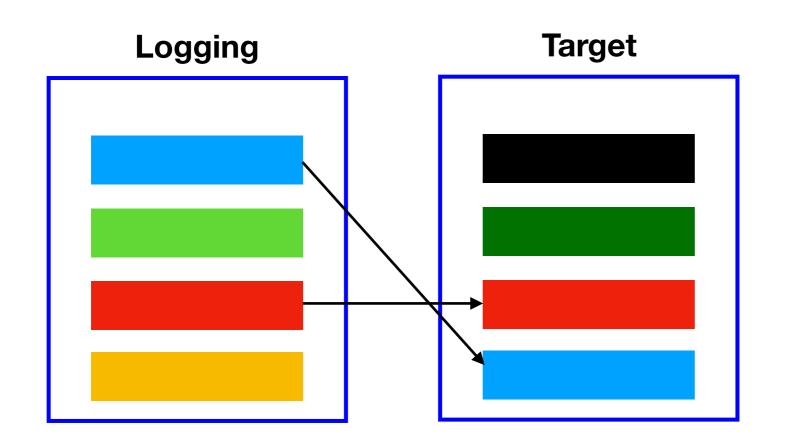
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- Uniform Q gives O(B) variance
- Immediately gives decent algorithm (eps-greedy)

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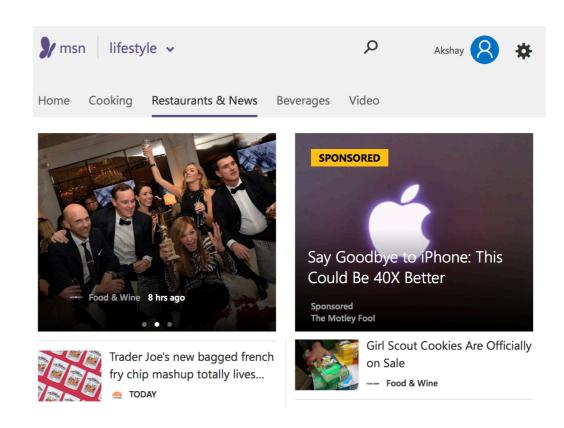
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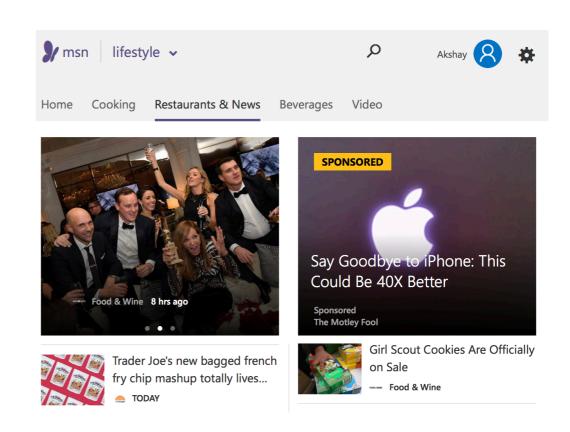
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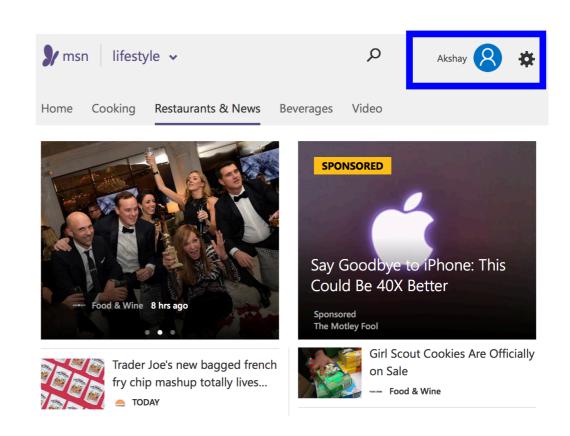
- Uniform Q gives O(B) variance
- Immediately gives decent algorithm (eps-greedy)
- We need more refined approach



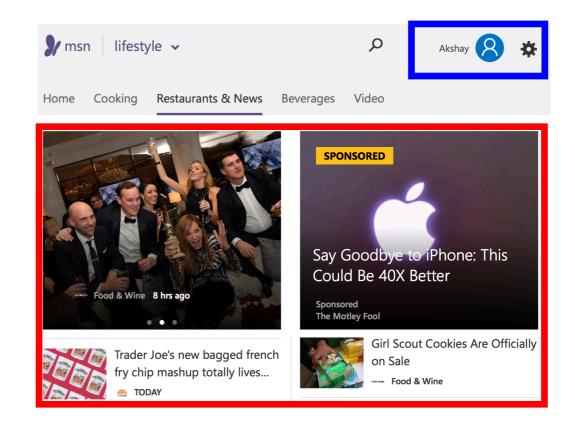
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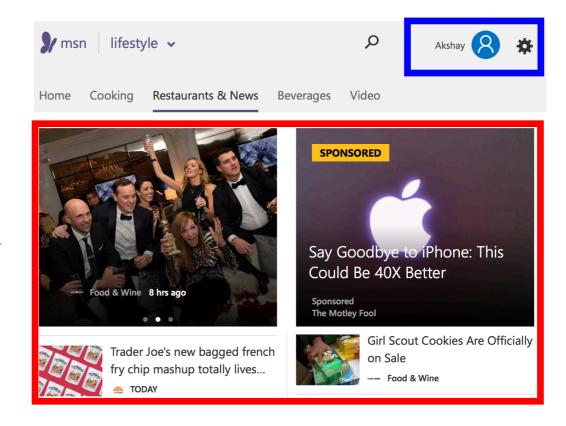
- 1. Observe context x_t
- 2.Play action
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- 1. Observe context x_t
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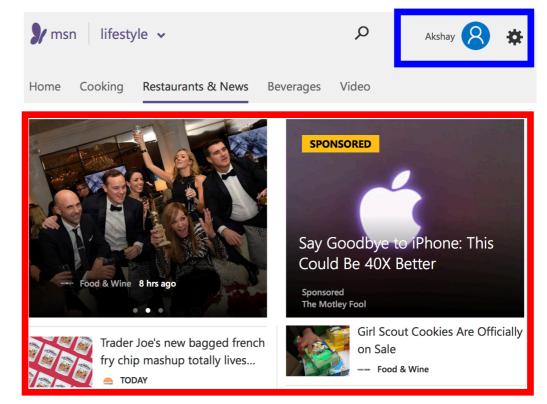


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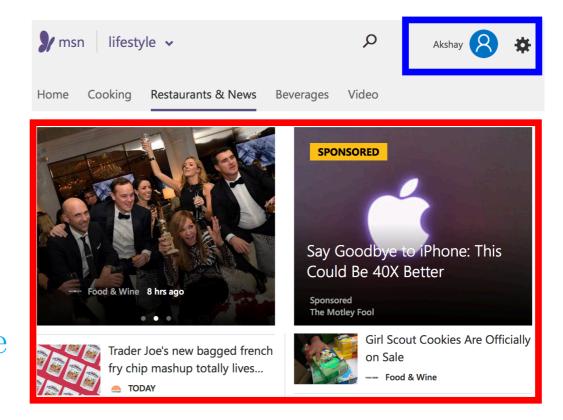
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B = number of simple actions

L = composite action length



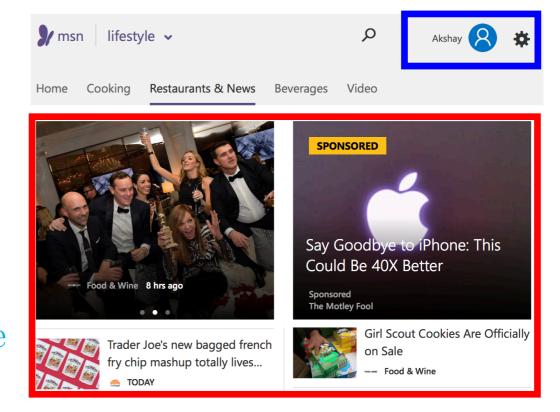
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Question: Improve performance by leveraging reward structure?

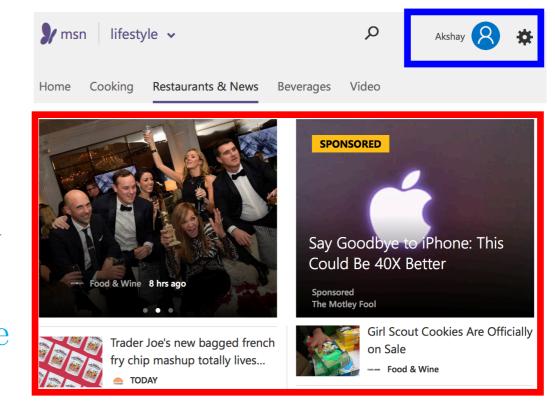
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Question: Improve performance by leveraging reward structure?

Challenges:

- Off-policy evaluation?
- Explore vs Exploit?
- Computational Efficiency?

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Theorem: If logging close to uniform, can estimate target with BL/ϵ^2 samples

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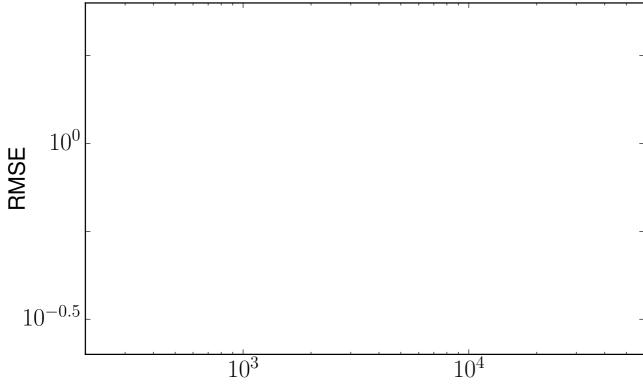
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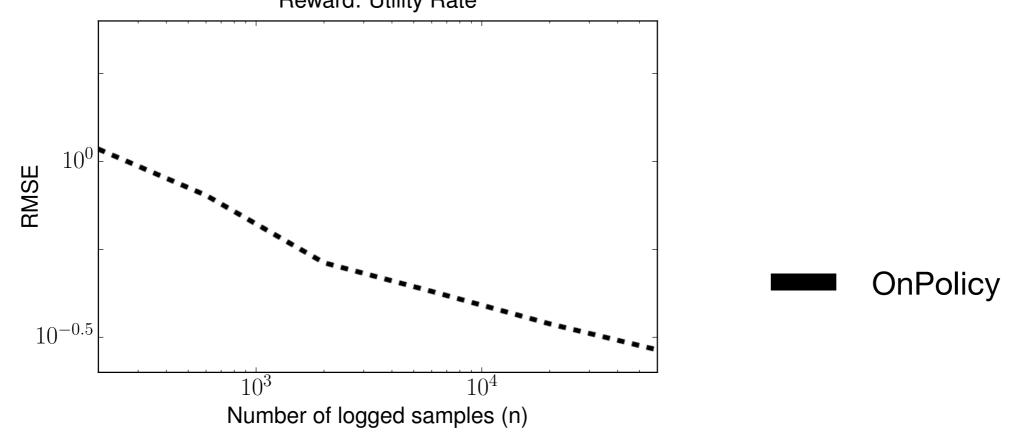
Number of logged samples (n)

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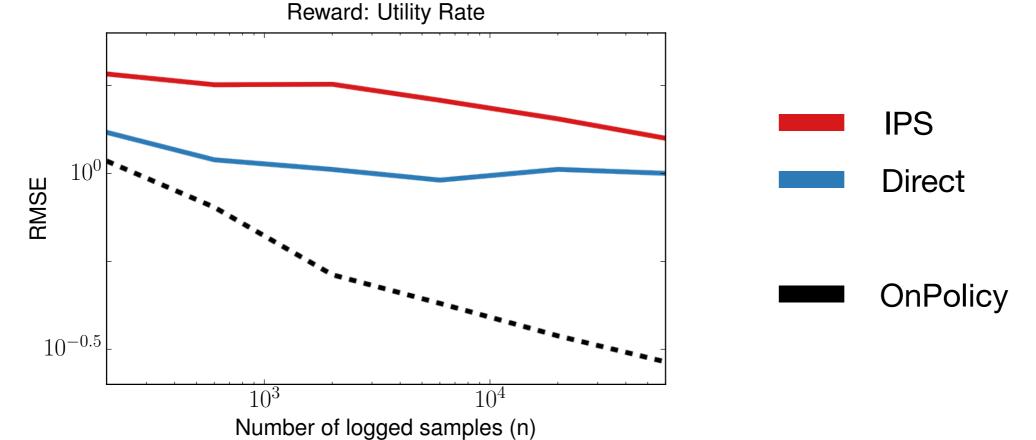


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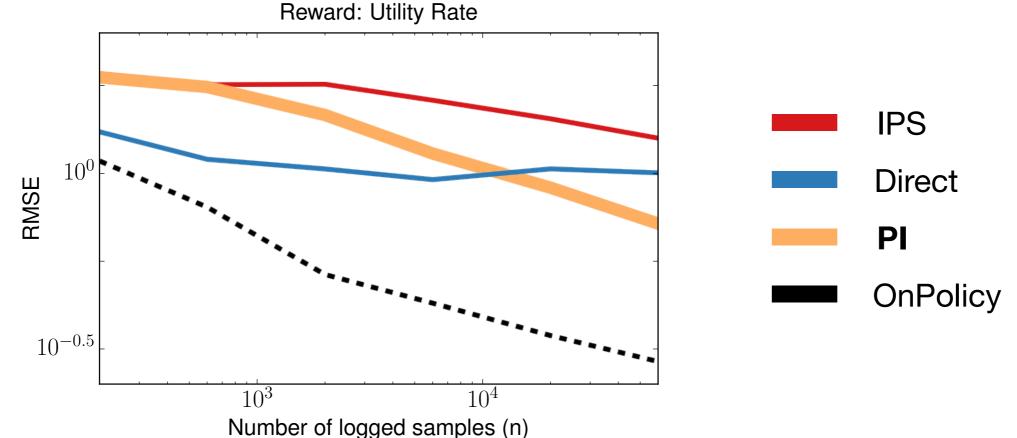


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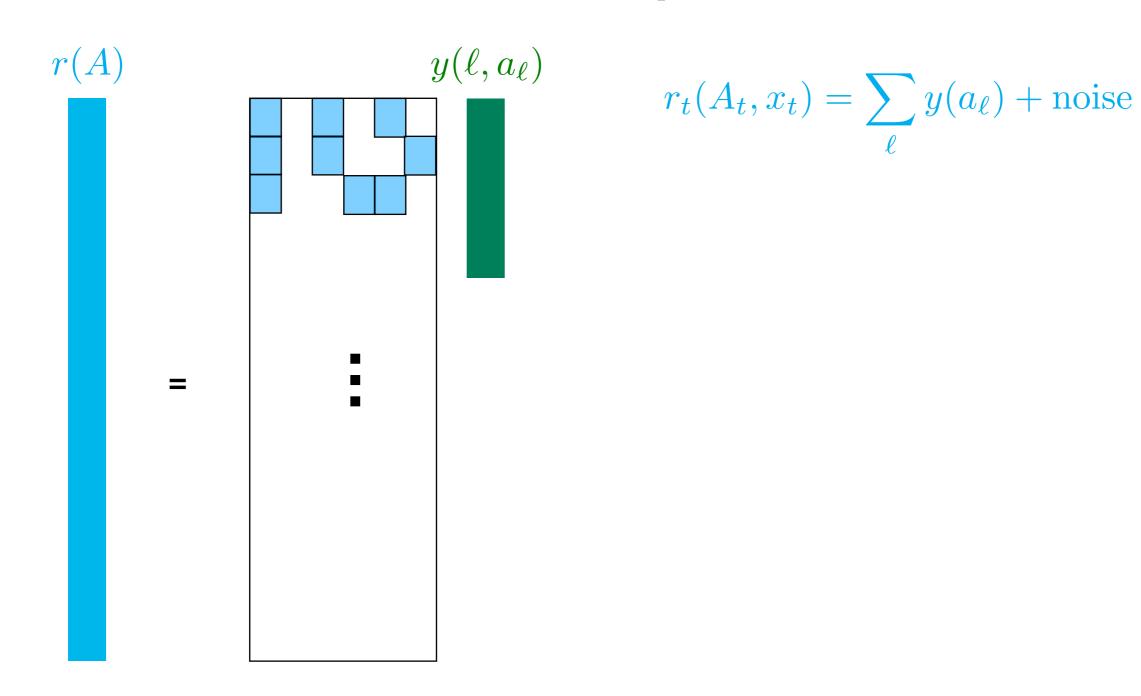
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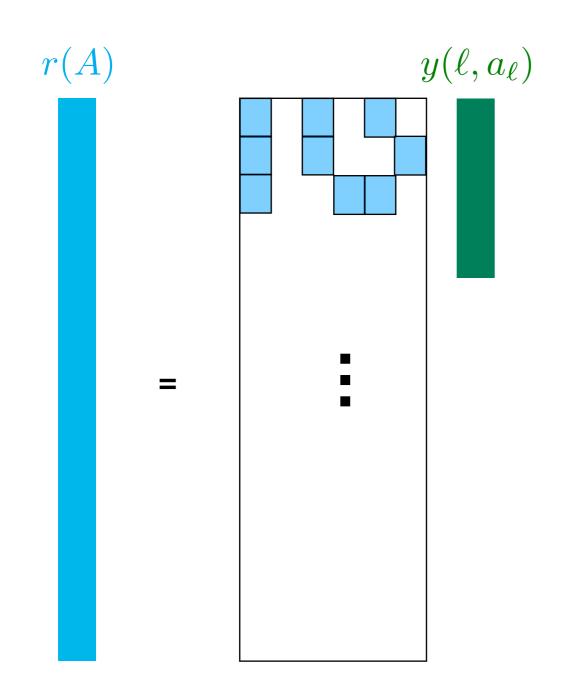
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Techniques

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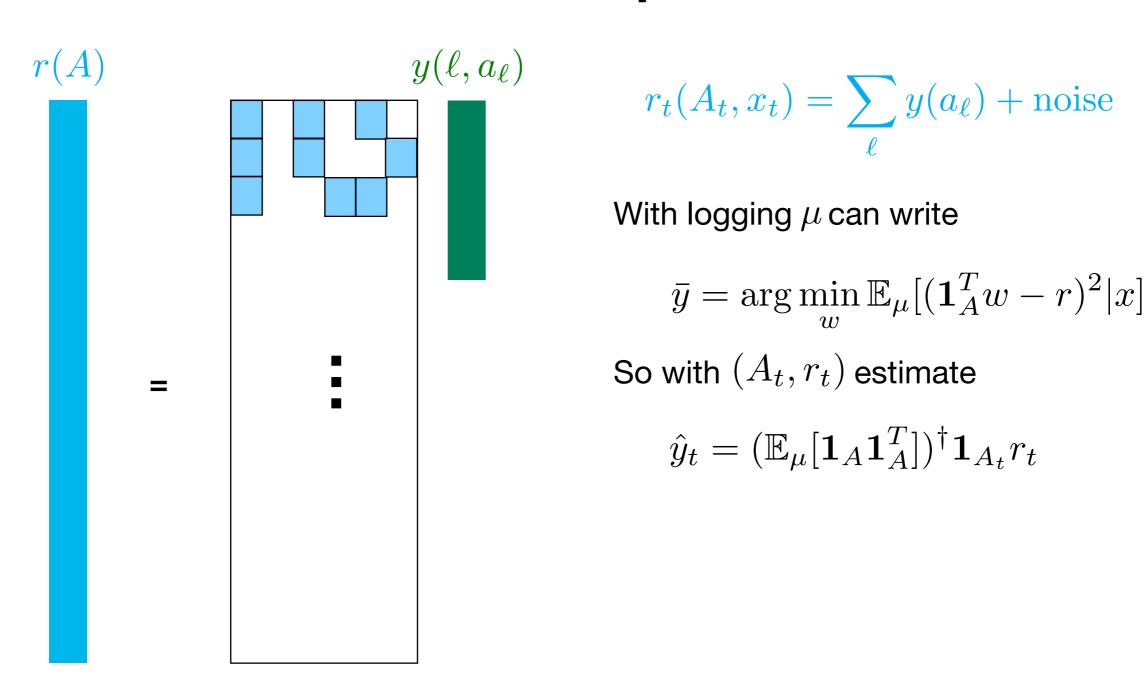


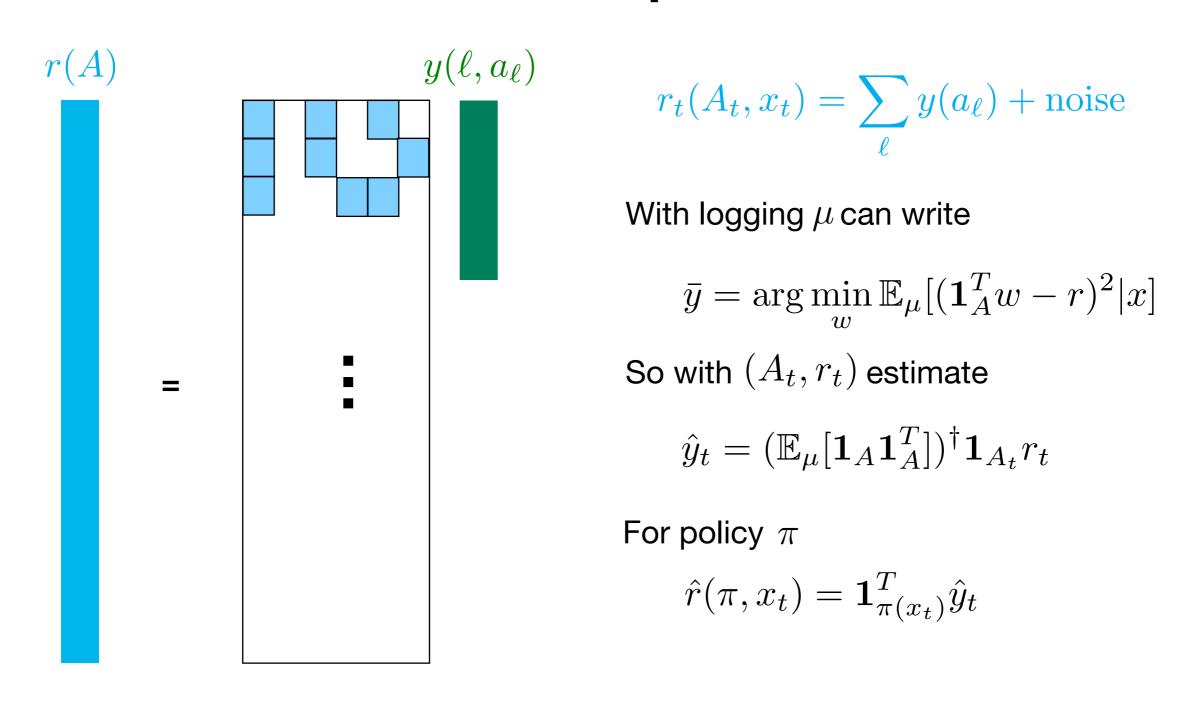


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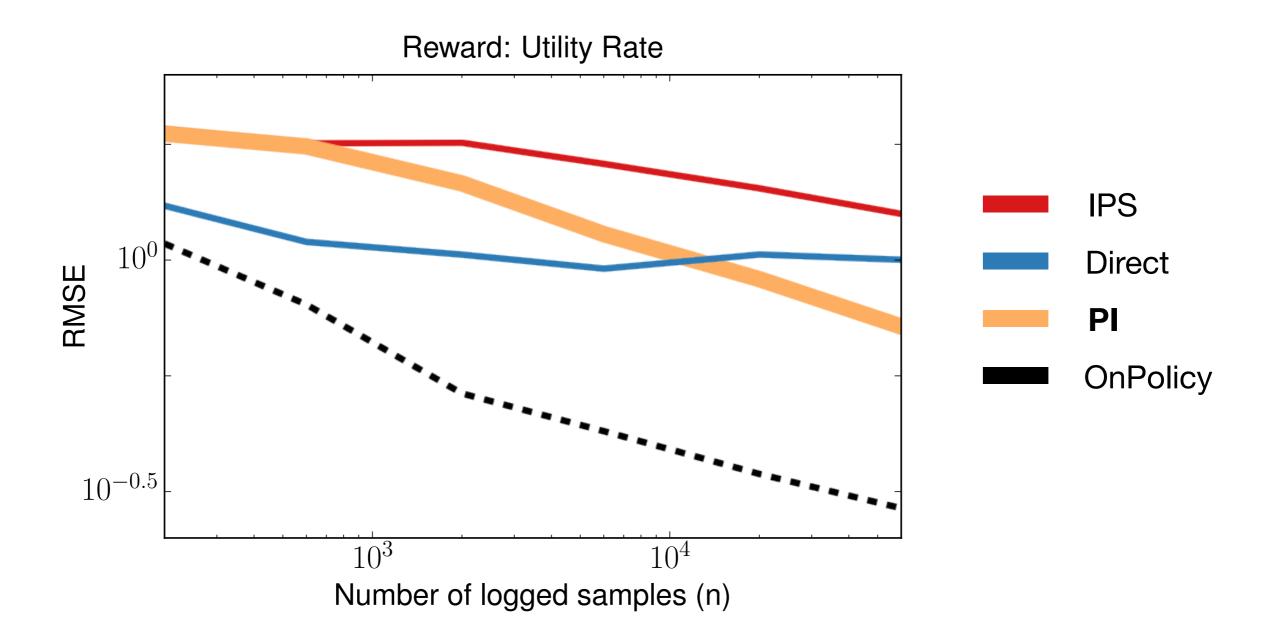
With logging μ can write

$$\bar{y} = \arg\min_{w} \mathbb{E}_{\mu}[(\mathbf{1}_{A}^{T}w - r)^{2}|x]$$

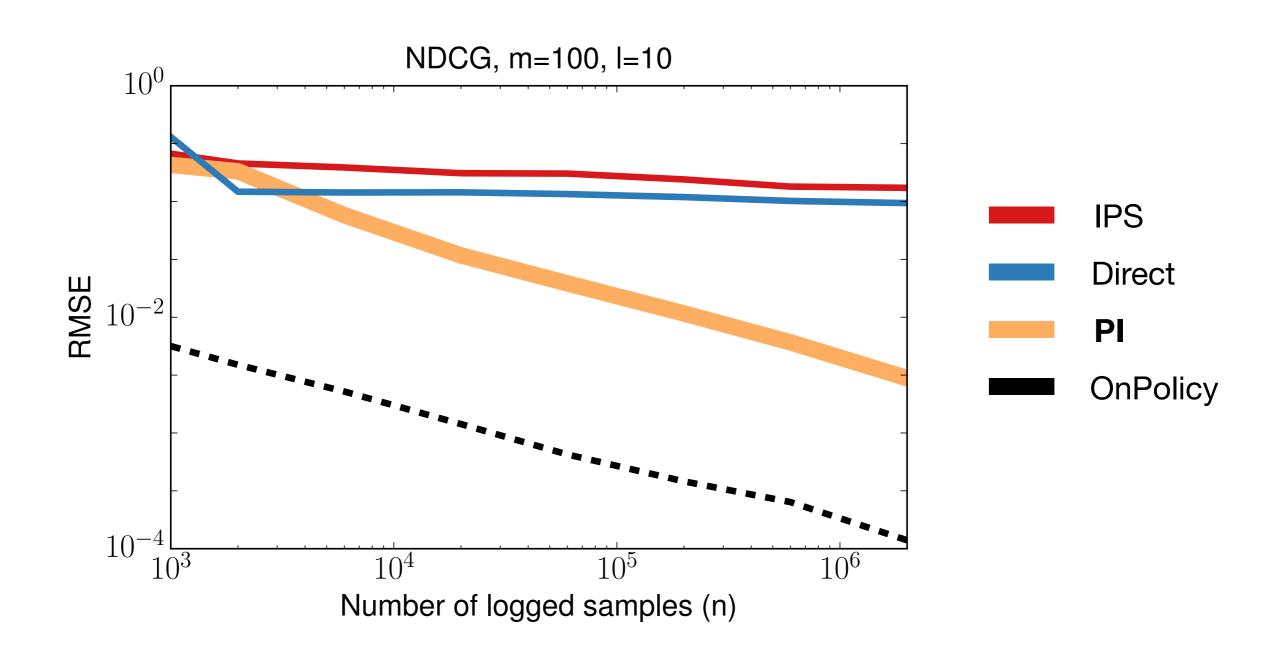




Experiment



Experiment



• Use PI estimator to obtain, with \boldsymbol{x}_t

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PI finds good targets to optimize metric!

Naive CB Semibandits Combinatorial

Parameters: T rounds, B simple actions, composite action length L

	Naive CB	Semibandits	Combinatorial
Off-Policy Eval	B^L	B	BL

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Open

• Efficient CCB with \sqrt{T} regret